

# Direct Simulation of the motion of rigid fibers in viscous fluid

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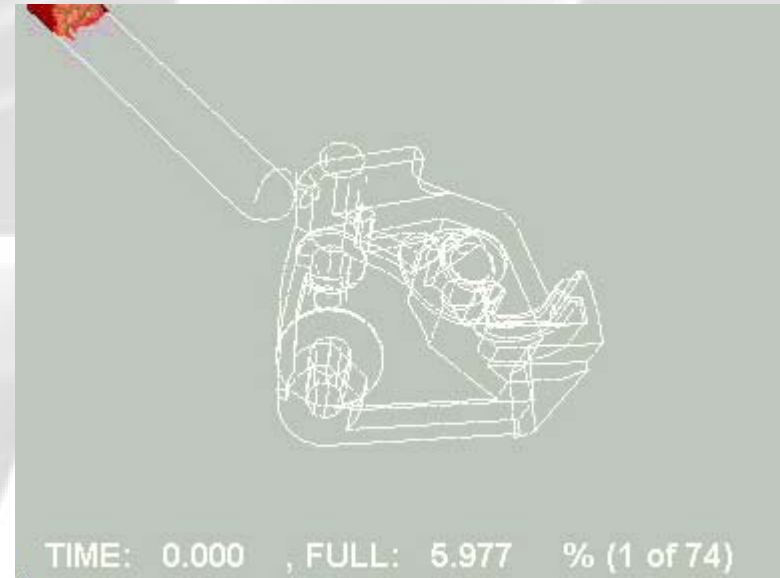
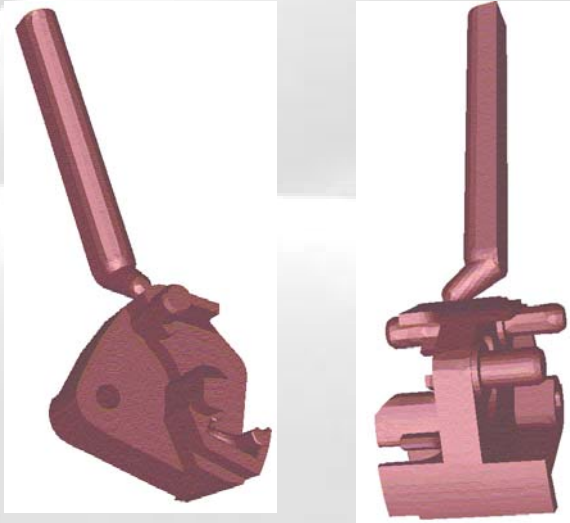
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# Introduction (1)

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- **Injection of thermoplastic**



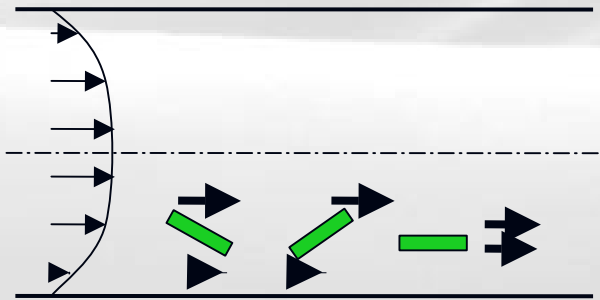
- **Injection of fiber-reinforced polymer**

- use the same process as classical thermoplastic
- complex composite products with improved mechanical properties
- mechanical properties depend on fiber orientation

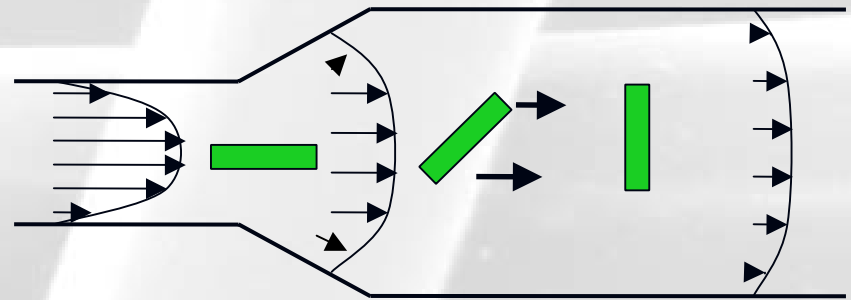
## Introduction (2)

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- **Fiber orientation in flow motion**



**Shear flow**



**Elongational flow**

# Background & Motivations

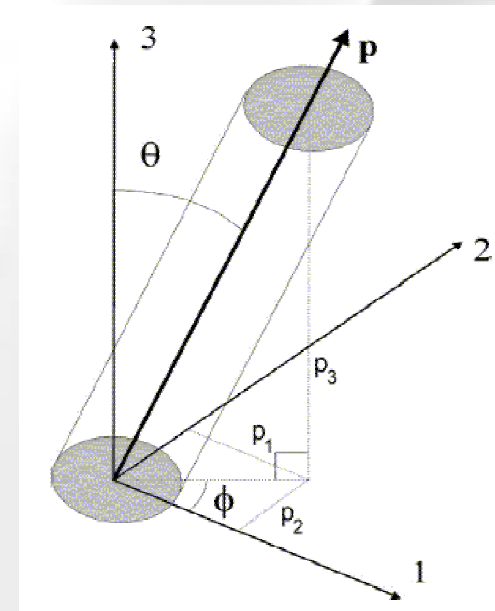
## ■ Macroscopic modelling

- Dilute suspension → **Jeffery's equation** [Jeffery 1922]

Newtonian fluid –slender body theory

$$\frac{dp}{dt} = \Omega p + \lambda (\dot{\epsilon} p - (\dot{\epsilon} : [p \otimes p]) p)$$

$f(\beta = \text{aspect ratio})$



**p** orientation vector

- Semi-concentrated suspension → **Folgar and Tucker's equation** [Folgar 1984]

**Population of fiber :** 
$$a_2 = \int_p \psi(p) p \otimes p dp = \frac{1}{N} \sum_{k=1}^N p_k \otimes p_k$$

$$\frac{Da_{\underline{\underline{2}}}}{Dt} = \underline{\underline{\Omega}} a_{\underline{\underline{2}}} - a_{\underline{\underline{2}}} \underline{\underline{\Omega}} + \lambda (\underline{\underline{\dot{\epsilon}}} a_{\underline{\underline{2}}} + a_{\underline{\underline{2}}} \underline{\underline{\dot{\epsilon}}} - 2 \underline{\underline{\dot{\epsilon}}} : a_{\underline{\underline{4}}}) + 2C_I \underline{\underline{\dot{\epsilon}}} (I_d - 3a_{\underline{\underline{2}}})$$

*fiber-fiber interaction term*



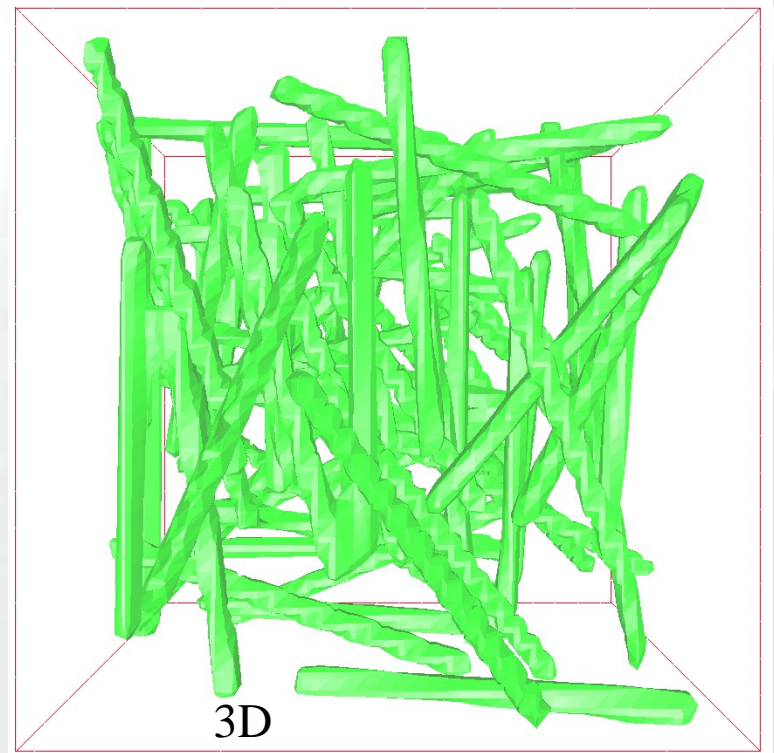
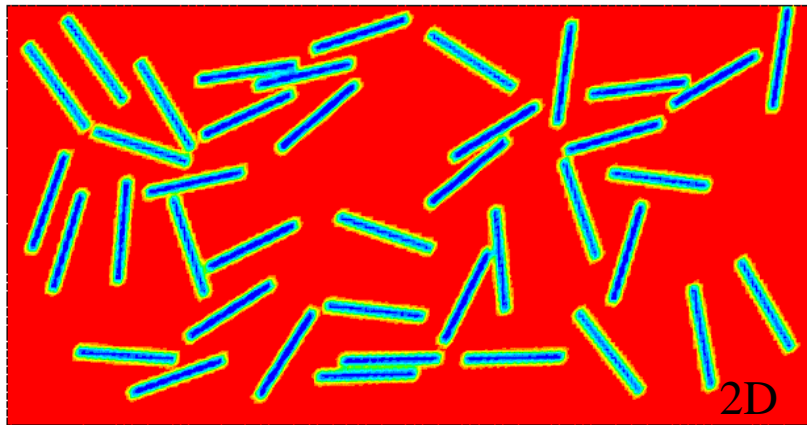
**Closure approximation, Ci ?**

# Objectives : Micromechanic modelling approach

## Micromechanic approach → Direct simulation

Simulate directly the motion of a dense population of fiber in a REV

Particle interactions are given by a fluid-structure coupling



Gives macroscopic informations  
on tensor  $a_2$  and rheological  
properties

# Numerical Procedure

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t

1. **Computation of velocity field with Rem3D**  
*finite element method for the Stokes equation with multi-domain approach  
(no inertia, no gravity)*
2. **Update particle position**  
*particle method*
3. **Computation of characteristic functions associated to each domain**  
*voxelisation method*

t +  $\Delta t$

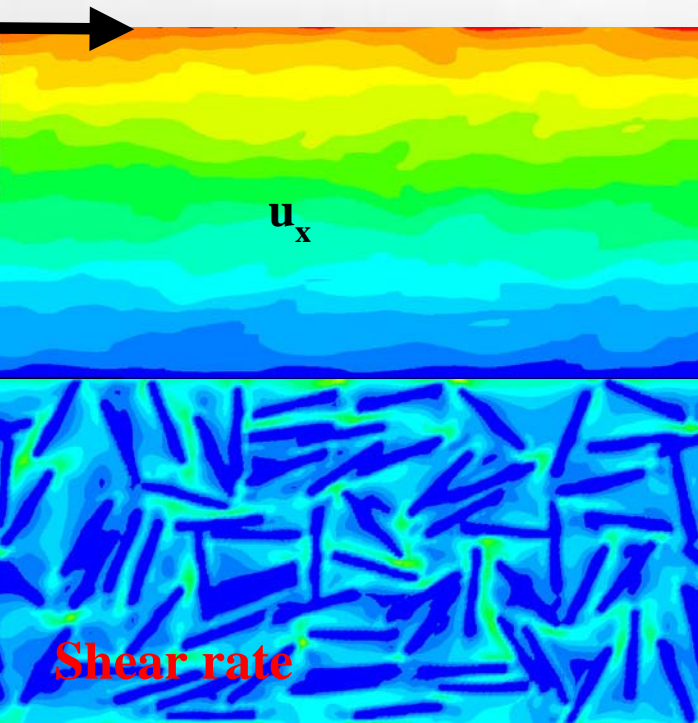
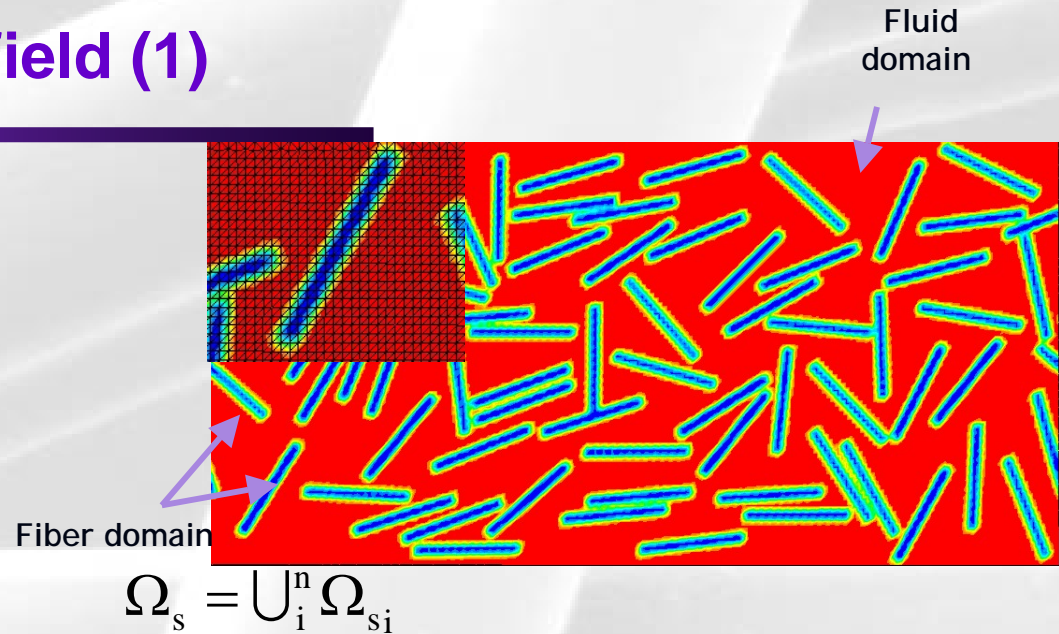
- **Numerical approach similar to Glowinski & Joseph's modelling** [Glowinski 1999]  
(Fictitious domain method for particulate flows)

# Computation of Velocity field (1)

## 1) Characteristic function

$$1_{\Omega_j}(\mathbf{x}, t) = \begin{cases} 1 & \mathbf{x} \in \Omega_j \\ 0 & \mathbf{x} \notin \Omega_j \end{cases}$$

$j = \text{fluid or solid (fibers)}$



## 2) Velocity field

$$\nabla \cdot \sigma = 0$$

$$\int_{\Omega} 1_{\Omega_f} 2\eta \varepsilon(u) : \varepsilon(v) d\Omega + \int_{\Omega} 1_{\Omega_s} \mathbf{r} \varepsilon(u) : \varepsilon(v) d\Omega$$

$$- \int_{\Omega} p \nabla \cdot v d\Omega = 0$$

Penalization  $\sim 10^3 \eta$   
 $\varepsilon(u) = 0$

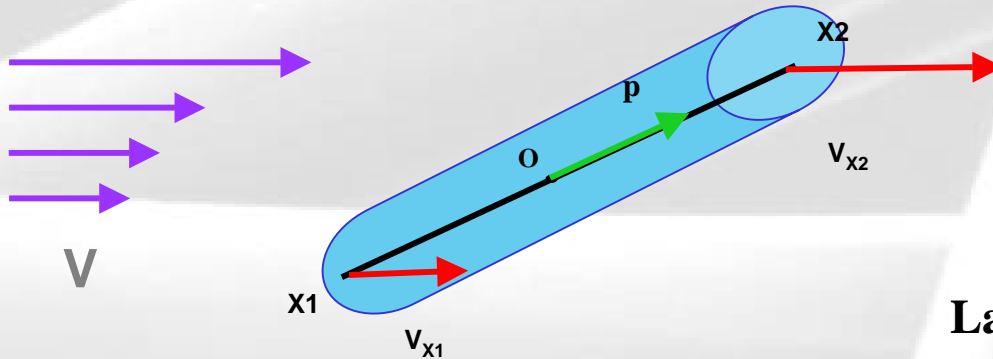
$$\nabla \cdot \mathbf{u} = 0$$

$$- \int_{\Omega} q \nabla \cdot u d\Omega = 0$$



# Update fiber position and orientation (2)

## Particle method



$$X_i(t + \Delta t) = X_i + V_{X_i} \Delta t$$

Langrangian updating of the position of the two extremities of each fiber

## Rigid motion

$$\vec{p} = \frac{\overrightarrow{X_2 X_1}}{\|\overrightarrow{X_2 X_1}\|} \quad \text{Vector orientation}$$

$$O = \frac{X_1 + X_2}{2} \quad \text{Fiber center}$$

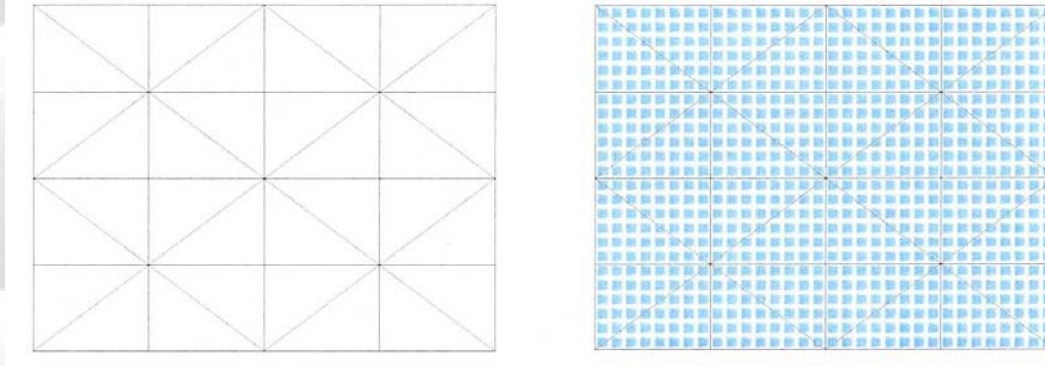
## Advantages

- Perfect rigid motion of each fiber
- Conservation of the length
- No numerical diffusion



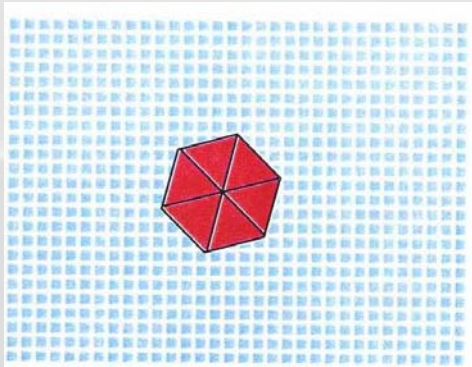
# Computation of Characteristic Function (3)

## Voxelisation method

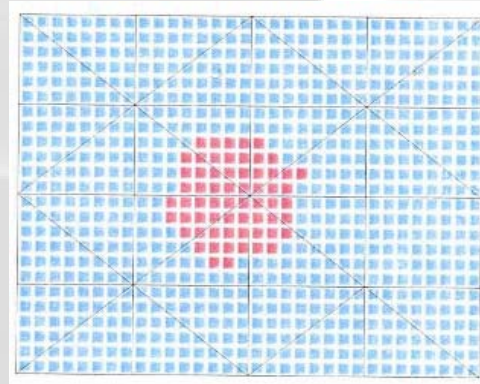


Cavity mesh

Voxelisation



Add fiber mesh

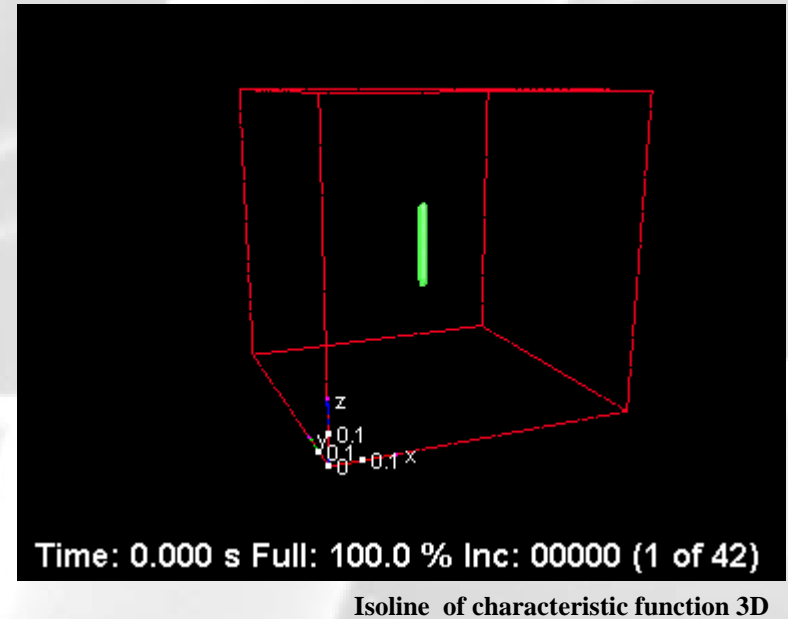
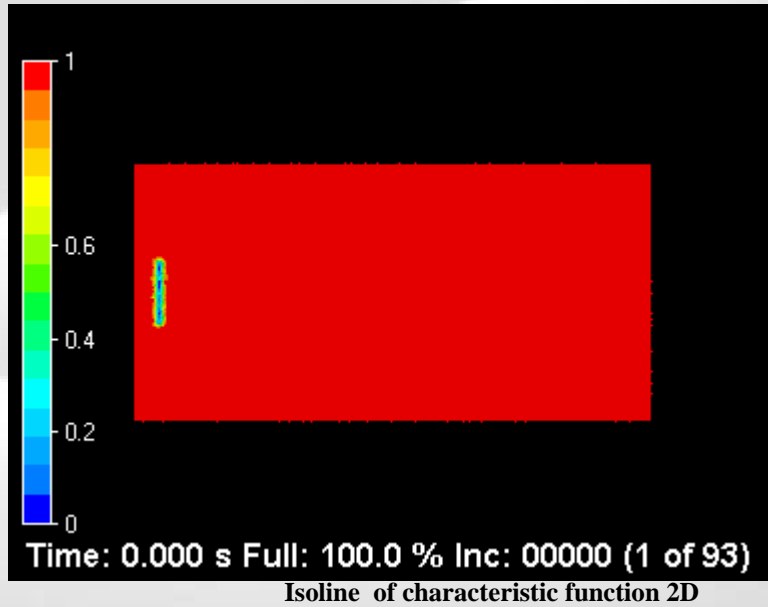


switch on pixels

0	0	0	0
0	0	0	0
0	0.6	0.3	0
0	0.8	0.23	0
0	0.7	0.28	0
0	0.55	0.4	0
0	0	0	0
0	0	0	0

Get values

# Single Fiber Motion in shear flow

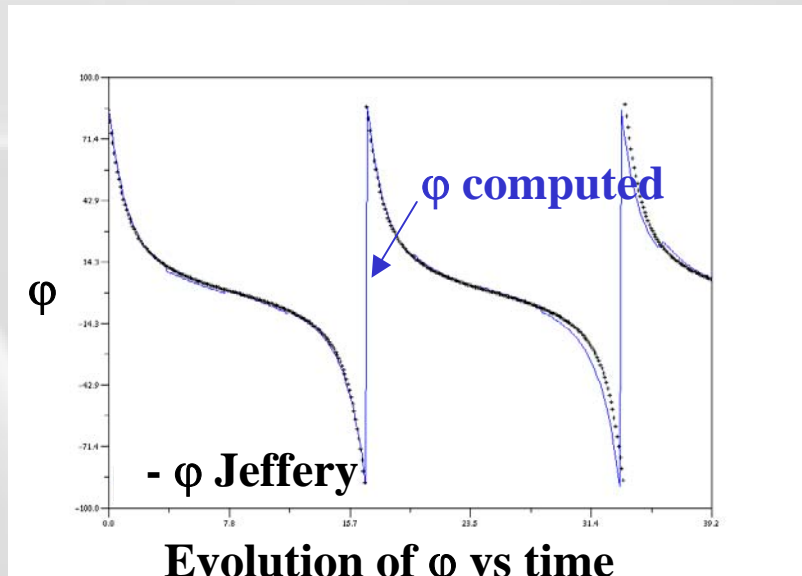


Shear flow, Periodic Cell  
aspect ratio  $\beta=10$

Find Jeffery's orbit for a shear flow

➡ Periodic motion

$$T = \frac{2\pi}{\dot{\gamma}} \left( \beta + \frac{1}{\beta} \right)$$

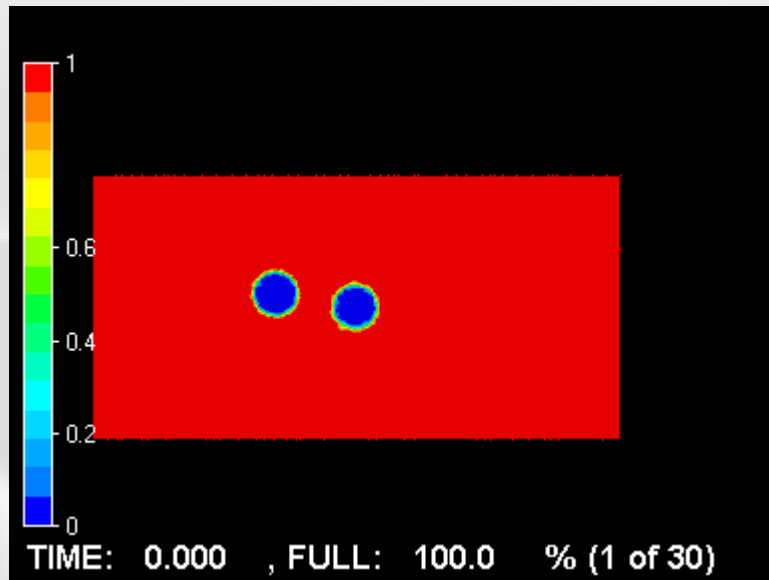


# Hydrodynamical Interactions

It is not necessary to have an explicit form (as in [Yamane 1994] , [Fan 1998])

- drag forces
- lubrication forces (short range interactions)

→ An example of hydrodynamical interactions

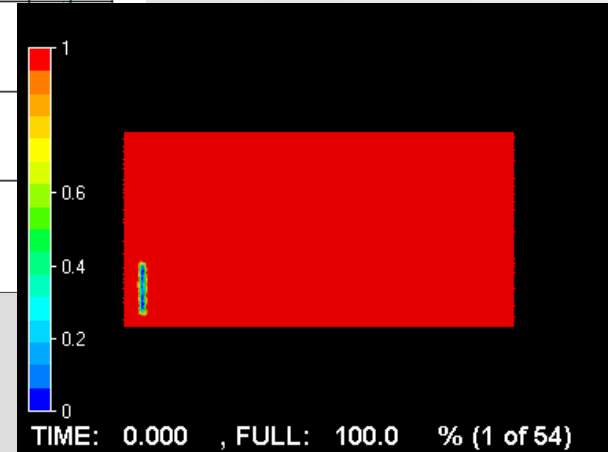
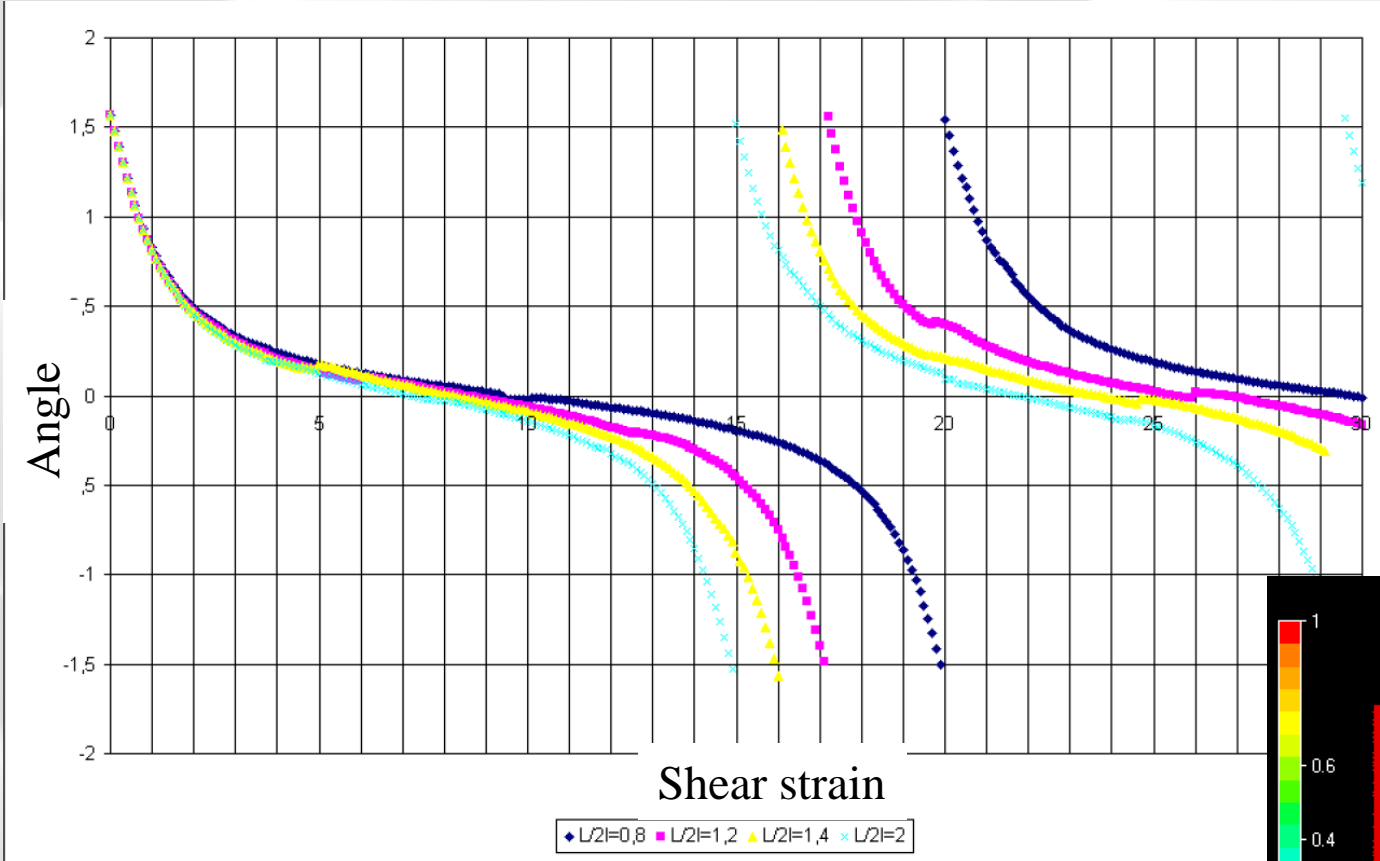
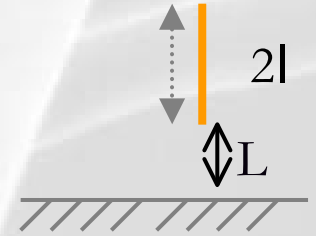


The central particle moves due to hydrodynamical interactions

Sphericals particles in Couette Flow

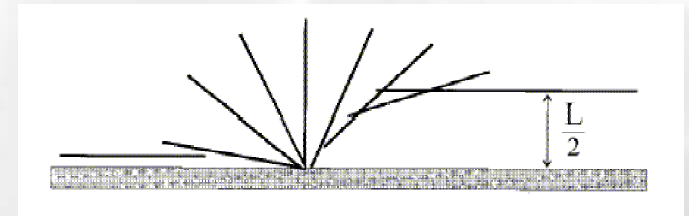
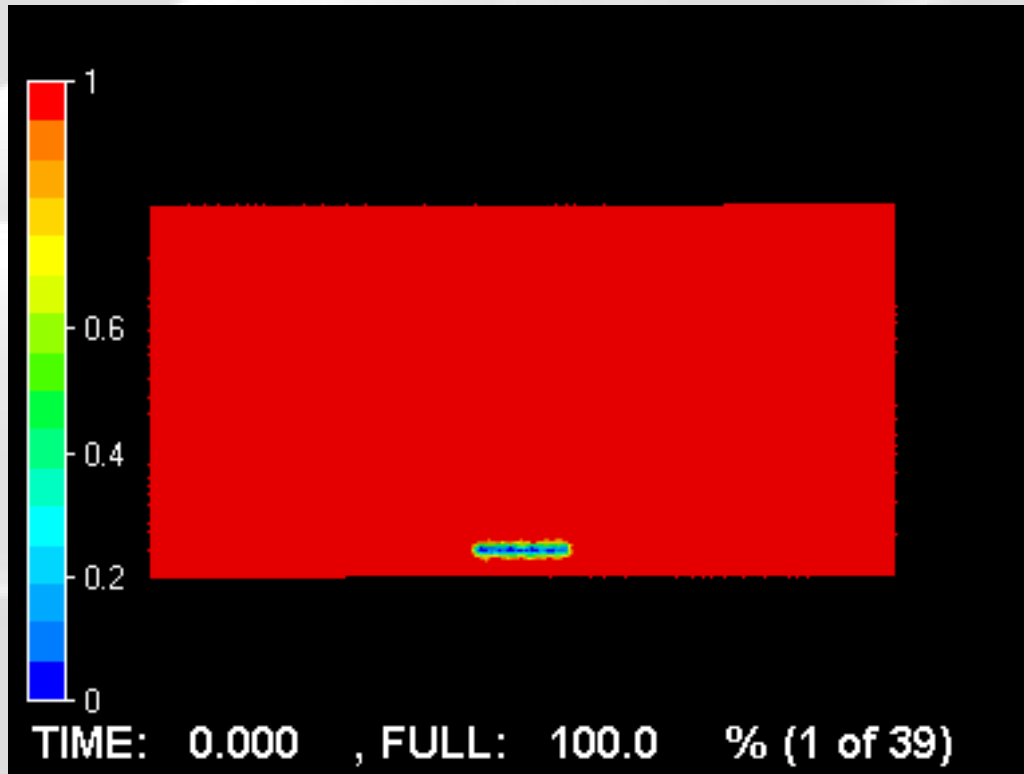
# Fiber – Wall interaction (1)

- Fiber initially perpendicular to the wall



## Fiber – Wall interaction (2)

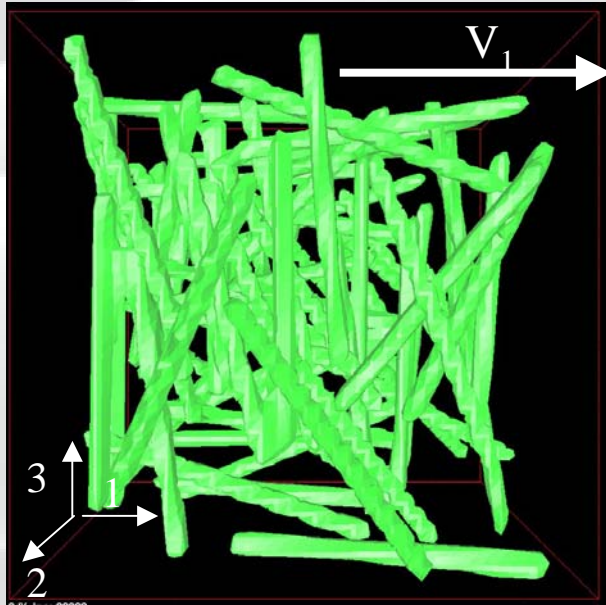
- Fiber initially parallel to the wall



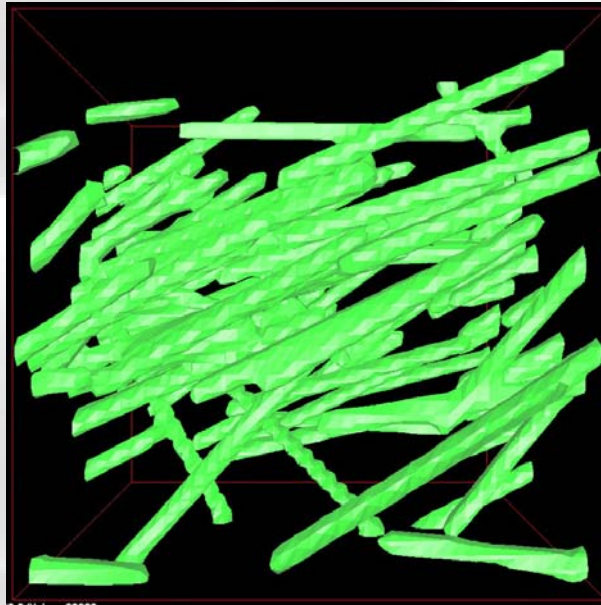
Fiber migration and alignment near the wall

# Statistical studies - 3D example -

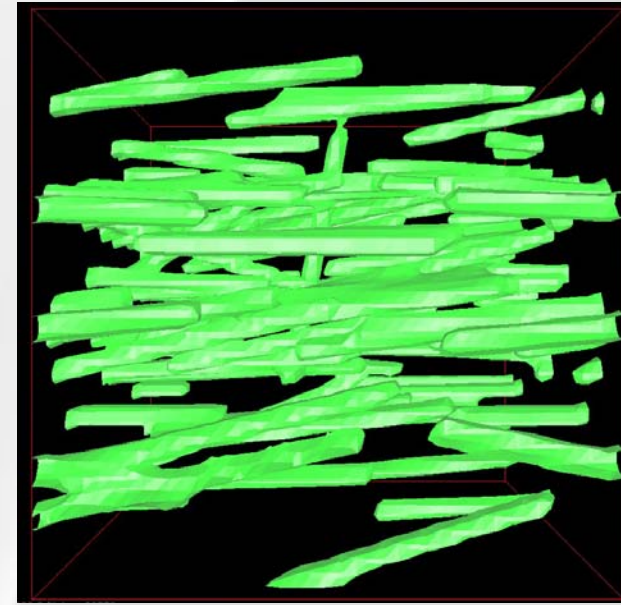
- Aspect ratio  $\beta = 12$ , concentrated suspension
- Shear flow



Initial time



Shear strain 5



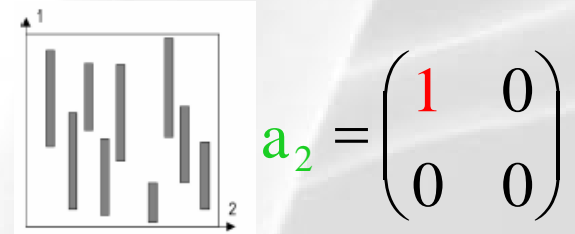
Shear strain 10



Get  $a_2$  and  $a_4$  on time

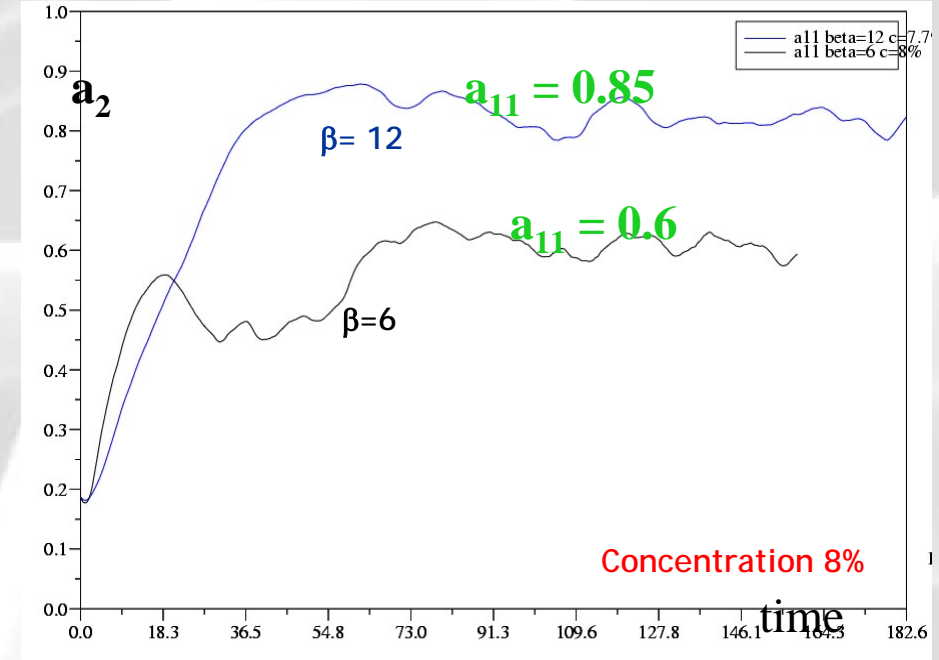
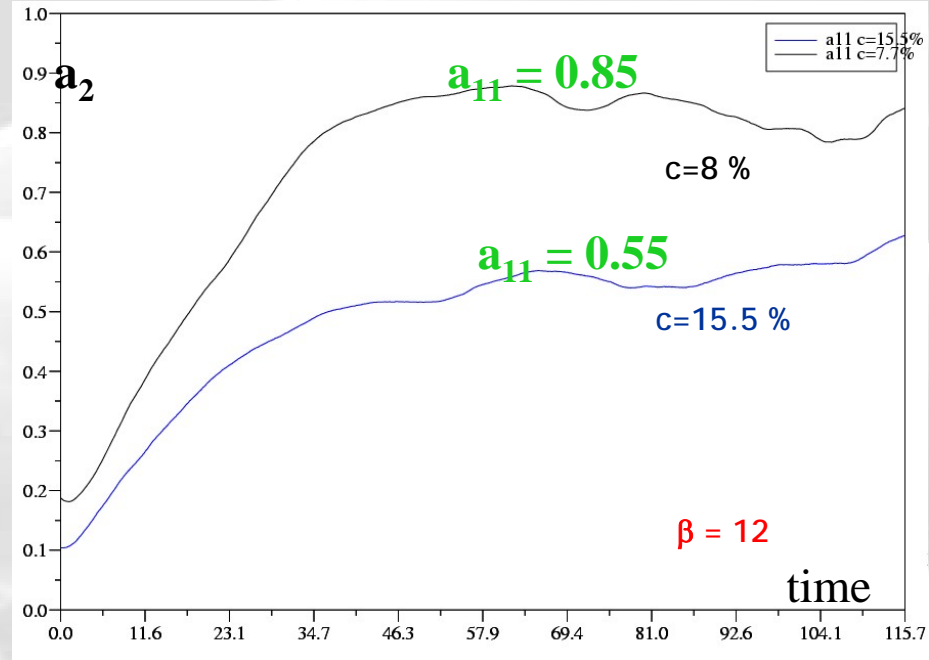
$$a_2 = \frac{1}{60} \sum_{k=1}^{60} p_k \otimes p_k$$

# Statistical studies (1) - Evolution of $a_2$ -



- Effect of the concentration

- Effect of the aspect ratio

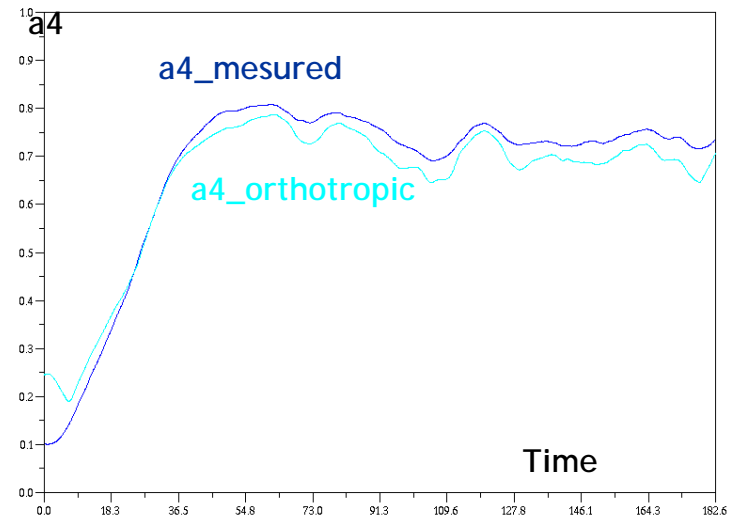
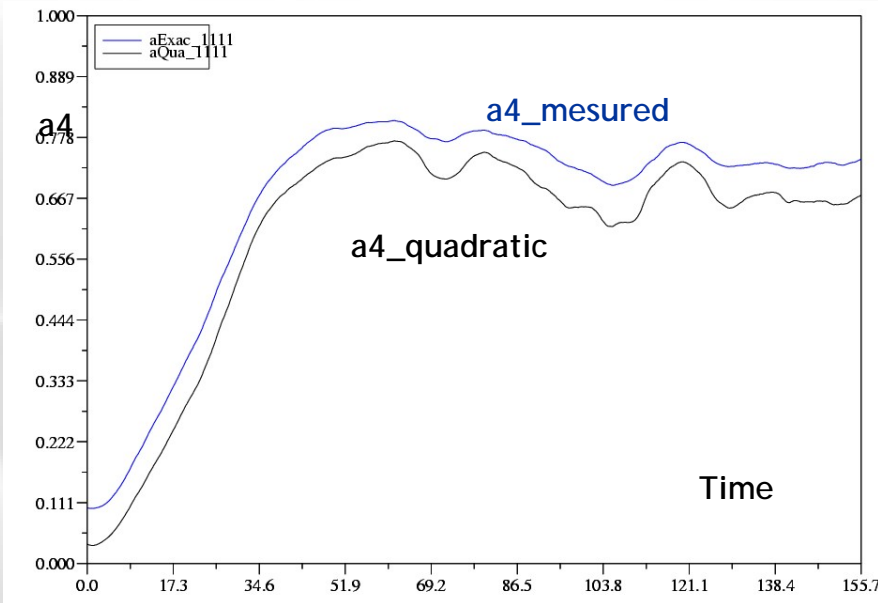


- Sensibility of simulations to the concentration and the aspect ratio
  - Interaction
  - Closure approximation



# Statistical studies (2) - Closure approximation -

- **Test of Closure approximation**
  - $\mathbf{a}_{4\_model} = \text{function}(\mathbf{a}_{2\_measured})$
  - **Comparison  $\mathbf{a}_{4\_measured}$  &  $\mathbf{a}_{4\_model}$**
- **60 fibers in shear flow,  $\beta = 12$**

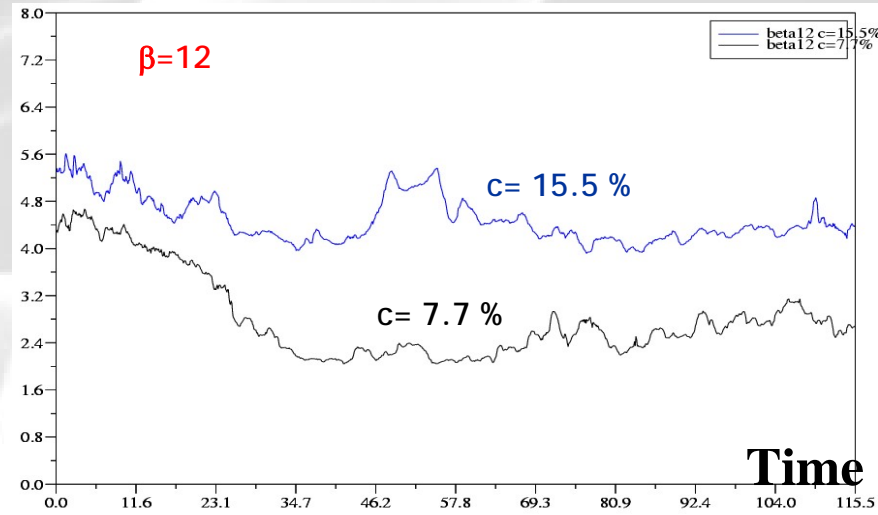


- **Quadratic closure : correct evolution in shear flow**
- **Orthotropic closure : more accurate**

# Statistical studies in progress (3) - Rheology-

## ■ Evolution of the viscosity in shear flow

$$\eta_{\text{apparent}} = \frac{\sigma_{\text{imposed}}}{\dot{\gamma}_{\text{apparent REV}}}$$



## ■ Evolution of the Cauchy stress tensor

$$\sigma = \sigma_{\text{fluid}} + \sigma_{\text{fibers}}$$

Newtonian fluids

$$\sigma_{\text{fibers}} = 2\eta_f \mathbf{N}_p \varepsilon(\mathbf{u}) : \mathbf{a}_4$$

Study of rheological parameters



# Conclusions

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- **We have developed a micromechanical modelling approach**
  - Simulate directly the motion of a dense population of fibers
  - Model the exact particle interaction by using a multi-domain approach
- **Very encouraging results for the**
  - Study of macroscopic parameters as :
    - ❖ interaction between particles
    - ❖ closure approximations
  - Study of the suspension's rheology :  $\eta$  and stress tensor
- **Next Step**
  - Multiple populations of fibers
  - Flexibility
  - Viscoelasticity