FINITE DIFFERENCE/FINITE VOLUME

Maximum principle (Discrete) and stability of the Finite difference scheme.

1D Poisson Equation

$$-\frac{\partial^2 \omega}{\partial \pmb{x}^2} = f(\pmb{x}), \quad \forall \pmb{x} \in (0,1), \text{ with } \omega(0) = \omega(1) = 0$$

Then we consider the numerical scheme defined as

$$+ \frac{2+c_1}{\delta \mathbf{x}^2} w_1 - \frac{1}{\delta \mathbf{x}^2} w_2 = \beta_1 f_1 - \frac{1}{\delta \mathbf{x}^2} w_{i-1} + \frac{2}{\delta \mathbf{x}^2} w_i - \frac{1}{\delta \mathbf{x}^2} w_{i+1} = f_i \quad \text{for } i = 2, \cdots, N-1$$

$$- \frac{1}{\delta \mathbf{x}^2} w_{N-1} + \frac{2+c_N}{\delta \mathbf{x}^2} w_N = \beta_N f_N$$

$$(0.1)$$

where $\delta \boldsymbol{x} > 0$, $c_1 \ge 0$, $c_N \ge 0$, β_1 and β_N are given parameters of the scheme and $f_i = f(\boldsymbol{x}_i)$ with $0 < \boldsymbol{x}_i < 1$ are given for $i = 1, \cdot, N$. Let use

$$oldsymbol{w}_h = egin{pmatrix} w_1\dots\ w_i\dots\ w_N \end{pmatrix} ext{ and } oldsymbol{b}_h = egin{pmatrix} eta_1f_1\dots\ f_i\dots\ eta_Nf_N \end{pmatrix}$$

- 1. Reformuate the numerical scheme under the form $\underline{A}_h w_h = b_h$ where $\underline{A}_h = \underline{A}_h^* + Diag\left(\frac{c_1}{\delta x^2}, 0, \cdots, 0, \frac{c_N}{\delta x^2}\right)$ is a matrix (to be defined) with a banded structure.
- 2. Verify that \underline{A}_h is symetric and positive defined (SPD) :

$$\boldsymbol{v} \cdot \underline{\boldsymbol{A}}_h \boldsymbol{v} \ge 0 \quad \forall \boldsymbol{v} \quad \text{ and } \quad \boldsymbol{v} \cdot \underline{\boldsymbol{A}}_h \boldsymbol{v} = 0 \Leftrightarrow \boldsymbol{v} = 0$$

- 3. For any positive vector $\boldsymbol{b} \ge 0$ and $\boldsymbol{b} \ne 0$, verify that the vector \boldsymbol{v}_b defined by $\underline{\boldsymbol{A}}_h \boldsymbol{v}_b = \boldsymbol{b}$ is such as $\boldsymbol{v}_b \ne 0$.
- 4. Define by p the minimum index where components of \boldsymbol{v}_b are minimal. Verify that either p = 1 or p = N and in any case $\boldsymbol{v}_b \ge 0$.
- 5. Appling the previous result for canonical basis $\boldsymbol{v}_b = \boldsymbol{e}_i : i = 1, \cdots, N$ find that $\underline{\boldsymbol{A}}_h$ is a monotone matrix (invertible and $\underline{\boldsymbol{A}}_h^{-1}$ is positive : $(\underline{\boldsymbol{A}}_h^{-1})_{ij} \ge 0$).
- 6. Verify that $(\underline{A}_{h}^{\star})^{-1} (\underline{A}_{h})^{-1} = (\underline{A}_{h})^{-1} (\underline{A}_{h} \underline{A}_{h}^{\star}) (\underline{A}_{h}^{\star})^{-1}$ so that $(\underline{A}_{h}^{\star})^{-1} (\underline{A}_{h})^{-1}$ is a positive matrix and therefore $(\underline{A}_{h})^{-1} \leq (\underline{A}_{h}^{\star})^{-1}$ and

$$\left\|\underline{\boldsymbol{A}}_{h}^{-1}\right\|_{\infty} = \max_{i=1}^{N} \left(\sum_{j=1}^{N} \left|\left(\underline{\boldsymbol{A}}_{h}^{-1}\right)_{ij}\right|\right) = \max_{i=1}^{N} \left(\sum_{j=1}^{N} \left(\underline{\boldsymbol{A}}_{h}^{-1}\right)_{ij}\right) \leq \left\|\left(\underline{\boldsymbol{A}}_{h}^{\star}\right)^{-1}\right\|_{\infty}$$

7. Verify that $\underline{A}_{h}^{\star} \boldsymbol{v} = 1$ for $\boldsymbol{v}_{i} = T(i\delta\boldsymbol{x})$ with $T(\boldsymbol{x}) = \frac{\boldsymbol{x}(1-\boldsymbol{x})}{2}$ and conclude that

$$\left\| \left(\underline{A}_{h}^{\star}\right)^{-1} \right\|_{\infty} = \max_{i=1}^{N} \boldsymbol{v}_{i} \leq \frac{1}{8}, \quad \text{therefore} \quad \left\| \left(\underline{A}_{h}\right)^{-1} \right\|_{\infty} \leq \frac{1}{8}$$