# Statistical estimation of the division rate of a size-structured population 

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(2) Goldenshluger and Lepski's method
(3) Other steps
(4) Main results

## The informal problem and the PDE translation

- A cell grows.
- Depending on its size $x$, the cell has a certain chance to divide itself in 2 offsprings, ie 2 cells of size $x / 2$.
- We are interesting by the evolution of the whole population of cells, each of them having this behavior.


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## Size-Structured Population Equation (finite time)

$$
\left\{\begin{array}{l}
\frac{\partial}{\partial t}(n(t, x))+\kappa \frac{\partial}{\partial x}(g(x) n(t, x))+B(x) n(t, x)=4 B(2 x) n(t, 2 x) \\
n(t, x=0)=0, \quad t>0 \\
n(0, x)=n_{0}(x), \quad x \geq 0
\end{array}\right.
$$

- $n(t, x)$ the "amount" of cells with size $x$ ( $\neq$ density),
- $g$ the "qualitative" growth rate of one cell: linear is $g=1 \ldots$
- $B$ is the division rate, which depends on the size


## Asymptotics of the PDE

It can be shown (Perthame Ryzhik 2005 for instance) that

- $n(t,$.$) grows exponentially fast ie I_{t}=\int n(t, x) d x$ asymptotically proportional to $e^{\lambda t}$,
- the renormalized $n(t, x) / I_{t}$ tends to a density $N$, which satisfies


## Size-Structured Population Equation (asymptotics)

$$
\left\{\begin{array}{l}
\kappa \frac{\partial}{\partial x}(g(x) N(x))+\lambda N(x)=\mathcal{L}(B N)(x), \\
B(0) N(0)=0, \quad \int N(x) d x=1,
\end{array}\right.
$$

where

- for any real-valued function $x \rightsquigarrow \varphi(x)$,

$$
\mathcal{L}(\varphi)(x):=4 \varphi(2 x)-\varphi(x)
$$

- $\kappa=\lambda \frac{\int_{\mathbb{R}_{+}} x N(x) d x}{\int_{\mathbb{R}_{+}} g(x) N(x) d x}$.


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- Analytical point of view: $N_{\epsilon}$ is a noisy version of $N$, less regular than $N$ (it is likely that no derivative exists) and $\left\|N-N_{\epsilon}\right\|_{2} \leq \epsilon$. (see Perthame, Zubelli, etc)


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- Statistical point of view: we observe a $n$-sample $X_{1}, \ldots, X_{n}$ of iid variables with density $N$.


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\hat{N}_{h}(x):=\frac{1}{n} \sum_{i=1}^{n} K_{h}\left(x-X_{i}\right),
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$K_{h}=\frac{1}{h} K(. / h)$.
Bias-Variance decomposition

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\mathbb{E}\left(\left\|N-\hat{N}_{h}\right\|_{2}\right) \leq\left\|N-K_{h} \star N\right\|_{2}+\frac{1}{\sqrt{n h}}\|K\|_{2}
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where $K_{h} \star N=\mathbb{E}\left(\hat{N}_{h}\right)$
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How to adaptively select $h$ ? Recent work of Goldenshluger and Lepski $(2009,2010)$ Here just a "toy" version, but that's exactly what we needed.

## Selection of bandwidth

Set for any $x$ and any $h, h^{\prime}>0$, $\hat{N}_{h, h^{\prime}}(x):=\frac{1}{n} \sum_{i=1}^{n}\left(K_{h} \star K_{h^{\prime}}\right)\left(x-X_{i}\right)=\left(K_{h} \star \hat{N}_{h^{\prime}}\right)(x)$,

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"estimator" of the bias term

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A(h):=\sup _{h^{\prime} \in \mathcal{H}}\left\{\left\|\hat{N}_{h, h^{\prime}}-\hat{N}_{h^{\prime}}\right\|_{2}-\frac{\chi}{\sqrt{n h^{\prime}}}\|K\|_{2}\right\}_{+}
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$$
\hat{h}:=\arg \min _{h \in \mathcal{H}}\left\{A(h)+\frac{\chi}{\sqrt{n h}}\|K\|_{2}\right\} \quad \text { and } \quad \hat{N}:=\hat{N}_{\hat{h}} .
$$

## First result

## Oracle inequality

If $\mathcal{H}=\left\{1 / \ell / \ell=1, \ldots, \ell_{\max }\right\}$ and if $\ell_{\text {max }}=\delta n$, if moreover $\|N\|_{\infty}<\infty$,
then for any $q \geq 1$,

$$
\begin{gathered}
\mathbb{E}\left(\|\hat{N}-N\|_{2}^{2 q}\right) \leq \\
\square_{q} \chi^{2 q} \inf _{h \in \mathcal{H}}\left\{\left\|K_{h} \star N-N\right\|_{2}^{2 q}+\frac{\|K\|_{2}^{2 q}}{(h n)^{q}}\right\}+ \\
\square_{q, \varepsilon, \delta,\|K\|_{2},\|K\|_{1},\|N\|_{\infty} \frac{1}{n^{q}}} .
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$$

## Estimation of $D=\frac{\partial}{\partial x}(g(x) N(x))$

If $K$ is differentiable, $\int K=1$ and $\int\left|K^{\prime}\right|^{2}<\infty$.

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Bias-Variance de composition:
$\mathbb{E}\left(\left\|D-\hat{D}_{h}\right\|_{2}\right) \leq\left\|D-K_{h} \star D\right\|_{2}+\frac{1}{\sqrt{n h^{3}}}\|g\|_{\infty}\left\|K^{\prime}\right\|_{2}$.
GL's trick

$$
\hat{D}_{h, h^{\prime}}(x):=\frac{1}{n} \sum_{i=1}^{n} g\left(X_{i}\right)\left(K_{h} \star K_{h^{\prime}}\right)^{\prime}\left(x-X_{i}\right),
$$

$$
\tilde{A}(h):=\sup _{h^{\prime} \in \tilde{\mathcal{H}}}\left\{\left\|\hat{D}_{h, h^{\prime}}-\hat{D}_{h^{\prime}}\right\|_{2}-\frac{\tilde{\chi}}{\sqrt{n h^{\prime 3}}}\|g\|_{\infty}\left\|K^{\prime}\right\|_{2}\right\}_{+},
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where, given $\tilde{\varepsilon}>0, \tilde{\chi}:=(1+\tilde{\varepsilon})\left(1+\|K\|_{1}\right)$.
Finally, we estimate $D$ by using $\hat{D}:=\hat{D}_{\tilde{h}}$ with

$$
\tilde{h}:=\operatorname{argmin}_{h \in \tilde{\mathcal{H}}}\left\{\tilde{A}(h)+\frac{\tilde{\chi}}{\sqrt{n h^{3}}}\|g\|_{\infty}\left\|K^{\prime}\right\|_{2}\right\} .
$$

## Result for the derivative $D$

## Oracle inequality for $D$

If $\tilde{\mathcal{H}}=\left\{1 / \ell / \ell=1, \ldots, \ell_{\max }\right\}$ and if $\ell_{\text {max }}=\sqrt{\delta^{\prime} n}$, if moreover $\|N\|_{\infty}$ and $\|g\|_{\infty}<\infty$, then for any $q \geq 1$,

$$
\begin{gathered}
\mathbb{E}\left(\|\hat{D}-D\|_{2}^{2 q}\right) \leq \square_{q} \tilde{\chi}^{2 q} \inf _{h \in \tilde{\mathcal{H}}}\left\{\left\|K_{h} \star D-D\right\|_{2}^{2 q}+\left[\frac{\|g\|_{\infty}\left\|K^{\prime}\right\|_{2}}{\sqrt{n h^{3}}}\right]^{2 q}\right\} \\
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Let $c>0$,

$$
\hat{\kappa}=\hat{\lambda} \frac{\sum_{i=1}^{n} X_{i}}{\sum_{i=1}^{n} g\left(X_{i}\right)+c} .
$$

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$0=x_{0, k}<x_{1, k}<\cdots<x_{i, k}:=\frac{i}{k} T<\ldots<x_{k, k}=T$.
Set $\varphi_{i, k}=: \frac{k}{T} \int_{x_{i}, k}^{x_{i+1, k}} \varphi(x) d x$ for $i=0, \ldots, k-1$, and define by induction the sequence
$H_{i, k}(\varphi):=\frac{1}{4}\left(H_{i / 2, k}(\varphi)+\varphi_{i / 2, k}\right)$ with $\left\{\begin{array}{l}H_{0}(\varphi):=\frac{1}{3} \varphi_{1, k}, \\ H_{1}(\varphi):=\frac{4}{21} \varphi_{0, k}+\frac{1}{7} \varphi_{1, k}\end{array}\right.$

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$$
u_{i / 2}:= \begin{cases}u_{i / 2} & \text { if } i \text { is even } \\ \frac{1}{2}\left(u_{(i-1) / 2}+u_{(i+1) / 2}\right) & \text { otherwise. }\end{cases}
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Finally, we define

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\mathcal{L}_{k}^{-1}(\varphi)(x):=\sum_{i=0}^{k-1} H_{i, k}(\varphi) 1_{\left[x_{i, k}, x_{i+1, k}\right)}(x)
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Hence we are able to estimate $H=B N$ by

$$
\hat{H}=\mathcal{L}_{k}^{-1}(\hat{\kappa} \hat{D}+\hat{\lambda} \hat{N}) .
$$

## Oracle inequality for the estimation of $H=B N$

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- $\square_{\ldots} \frac{1}{n^{q / 2}}$.


## Rate of convergence for the estimation of $B$

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## Theorem

If one knows a bound $\alpha \geq s$, one can choose a kernel $K$ and a family of $\mathcal{H}$ and $\mathcal{H}^{\prime}$ independent of $s$ such that for any compact $[a, b]$ of $[0, T]$ (under technical assumptions),

$$
\mathbb{E}\left[\left\|(\tilde{B}-B) 1_{[a, b]}\right\|_{2}^{q}\right]=O\left(n^{-\frac{q s}{2 s+3}}\right) .
$$

## Simulations

$\mathrm{n}=5000$, Gaussian kernel, $B=3 \sqrt{x}, g=1$.




## Simulations




## Concluding remarks

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- Probabilistic interpretation not used: evolution of one cell look like TCP window size, but the whole population (?) $\rightsquigarrow$ chaos and not necessarily independence (work in progress of Hoffmann, Krell, Lepoutre ...)


## Concluding remarks

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- Calibration of GL's method not done, comparison with the L-curve method in analysis ( $\chi$ Nstep ?)

