

Generic Models for Topological Evidence Logics

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Topological models for epistemic logics

- Let (X, τ) be a topological space, Prop a set of propositional variables and $V : \text{Prop} \rightarrow \mathcal{P}(X)$ a valuation.
- Let us start with a language \mathcal{L} defined as follows:

$$\phi ::= p \mid \phi \wedge \psi \mid \neg\phi \mid K\phi,$$

with $p \in \text{Prop}$.

Interior semantics

- $\|p\| = V(p)$;
- $\|\phi \wedge \psi\| = \|\phi\| \cap \|\psi\|$;
- $\|\neg\phi\| = X \setminus \|\phi\|$;
- $\|K\phi\| = \text{Int } \|\phi\|$.

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- Generalisation of Kripke semantics for preordered frames: preorders are Alexandroff topologies.

From (X, \leq) consider the topology $\tau = \text{Up}(\leq)$.

We have: $x \in \text{Int } \|\phi\|$ iff $y \in \|\phi\|$ for all $y \geq x$.

- **Evidential** view of knowledge: knowing a proposition amounts to having a piece of evidence (i.e. an open set) that entails it.
- McKinsey & Tarski (1944) proved two important results to this respect:
 - The logic of topological spaces under this semantics is S_4 ;
 - The logic of a **single** dense-in-itself metrisable space (such as \mathbb{R}) under this semantics is S_4 .

But:

- The interior semantics equates “knowing” to “having evidence”.
- Some attempts at introducing belief (Steinsvold, 2006; Baltag et al., 2013) equate true belief to knowledge or confine us to work with really weird spaces.

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Topological evidence models

- Stalnaker (2006) proposes a logic for knowledge and belief.
- Following this and building on **evidence models** (van Benthem & Pacuit, 2011) a new framework is introduced by Baltag, Bezhanishvili, Özgün & Smets (2016) .
- The **dense interior semantics** allows us to talk about concepts such as **basic** and **combined evidence, justification, defeasible vs infallible knowledge...**
- Sentences are interpreted on **topological evidence models**.

A **topo-e-model** is a tuple

$$(X, \tau, E_0, V)$$

where (X, τ) is a topological space, E_0 a subbasis and V a valuation.

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- K : defeasible knowledge;
- B : belief;
- $[V]$: infallible knowledge;
- \square : having evidence;
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The dense interior semantics

- $x \in \llbracket K\phi \rrbracket$ iff $x \in \text{Int} \llbracket \phi \rrbracket$ and $\text{Int} \llbracket \phi \rrbracket$ is **dense**;
- $x \in \llbracket B\phi \rrbracket$ iff $\text{Int} \llbracket \phi \rrbracket$ is dense;
- $x \in \llbracket \forall \phi \rrbracket$ iff $\llbracket \phi \rrbracket = X$;
- $x \in \llbracket \Box \phi \rrbracket$ iff $x \in \text{Int} \llbracket \phi \rrbracket$;
- $x \in \llbracket \Box_0 \phi \rrbracket$ iff $x \in e \subseteq \llbracket \phi \rrbracket$ for some $e \in E_0$.

In this framework, knowing $P =$ having an evidence for P that **can't be defeated** by any other evidence (i.e. a **dense** evidence).

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The logic of some fragments

The knowledge fragment \mathcal{L}_K : S4.2.

The knowledge-belief fragment \mathcal{L}_{KB} : S4.2 axioms for K , KD45 axioms for B plus:

- (PI) $B\phi \rightarrow KB\phi$;
- (NI) $\neg B\phi \rightarrow K\neg B\phi$;
- (KB) $K\phi \rightarrow B\phi$;
- (CB) $B\phi \rightarrow \neg B\neg\phi$;
- (FB) $B\phi \rightarrow BK\phi$.

(This is the logic outlined in Stalnaker, 2006.)

The evidence fragment $\mathcal{L}_{\forall\Box\Box_0}$: S5 for $[\forall]$, plus S4 for \Box , plus:

- (4_{\Box_0}) $\Box_0\phi \rightarrow \Box_0\Box_0\phi$;
- (Universality) $[\forall]\phi \rightarrow \Box_0\phi$;
- (Factive evidence) $\Box_0\phi \rightarrow \Box\phi$;
- (Pullout) $(\Box_0\phi \wedge [\forall]\psi) \rightarrow \Box_0(\phi \wedge [\forall]\psi)$;

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Generic models

- Recall:

McKinsey & Tarski (1944)

The logic of topological spaces under the interior semantics is S_4 , and so is the logic of \mathbb{R} under the interior semantics.

- This result tells us that \mathbb{R} , as a topological space, is **generic** enough to capture the logic of topological spaces.
- How to apply this idea to our framework? First, let us formalise:

A topological space (X, τ) is a **generic model** for a language \mathcal{L} if the sound and complete \mathcal{L} -logic of topo-e-models is precisely the logic of the class

$$\{(X, \tau, E_0) : E_0 \text{ is a subbasis of } (X, \tau)\}.$$

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Theorems

- Any **dense-in-itself metrisable space** (X, τ) is a generic model for the knowledge fragment \mathcal{L}_K and the knowledge-belief fragment \mathcal{L}_{KB} .

Examples: \mathbb{R} , \mathbb{Q} , \mathbb{I} , the Baire space, the Cantor space, the binary tree...

The \mathcal{L}_K -logic of any of these spaces is $S4.2$.

- Any **dense-in-itself metrisable space** (X, τ) which is **idempotent** (i.e. homeomorphic to $(X, \tau) \oplus (X, \tau)$) is a generic model for the fragments $\mathcal{L}_{\forall\Box}$, $\mathcal{L}_{\forall K}$ and $\mathcal{L}_{\forall\Box\Box_0}$.

Examples: all of the above except \mathbb{R} and the binary tree.

So:

- Whatever is true in any of the logics defined earlier is true in any topo-e-model whose topological space is \mathbb{Q} , and conversely,
- Whatever is not provable in these logics has a countermodel based on \mathbb{Q} .

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$S_{4.2}$ is complete with respect to \mathbb{R} as a topo-e-model.

We use this (from Bezhanishvili \times 2, Lucero-Bryan & van Mill, 2018):

- Completeness wrt finite rooted $S_{4.2}$ Kripke frames (rooted preorder $B \cup$ final cluster A).
- Partition lemma: for each $n \geq 1$, \mathbb{R} can be partitioned in $\{U_1, \dots, U_n, G\}$, where G is a dense-in-itself set with dense complement and each U_i is open.
- There exists an open, continuous and surjective map $f : G \rightarrow B$.

We can extend f to a surjective map $\bar{f} : \mathbb{R} \rightarrow B \cup A$ such that:

- The preimage of an upset is is dense open set (*dense-continuous*);
- The image of a dense open set is an upset (*dense-open*).

If something can be refuted in $B \cup A$, we can construct a valuation using \bar{f} that refutes it in \mathbb{R} . Completeness follows.

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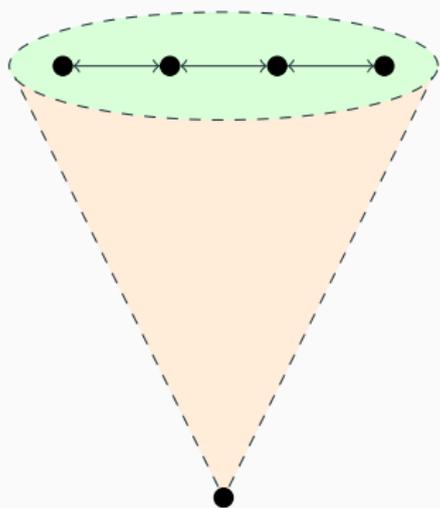
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COMPLETENESS PROOF (A DRAWING)

S4.2 is complete with respect to \mathbb{R} as a topo-e-model.



$$\begin{array}{c} \mathbb{R} \\ \parallel \\ A \xleftarrow{x \in U_i \mapsto a_i} U_1 \cup U_2 \cup U_3 \cup U_4 \\ \\ \cup \\ B \xleftarrow{f \text{ open and cont.}} G \end{array}$$

$$\bar{f} : \mathbb{R} \rightarrow A \cup B.$$

Two-agent topo-e-models

- Let us make this framework multi-agent.
- We will consider two epistemic agents (1 and 2) each of them having different sets of evidence on a common space X (τ_1 and τ_2).
- How do we account for defeasibility and infallible knowledge?
- A first **naive approach** would be to just use **density** as in the single agent case:

$$x \in \|\|K_i\phi\|\| \text{ iff } \exists U \in \tau_i, \text{ dense such that } x \in U \subseteq \|\|\phi\|\|.$$

- Two issues with this approach:
 - Same set of worlds is compatible with both agents' information.
 - The logic of this semantics contains theorems like

$$\hat{K}_1 K_1 p \rightarrow K_2 \hat{K}_1 K_1 p.$$

If agent 1 doesn't know that she doesn't know p , then agent 2 knows this fact.
We don't want this!

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- We want to account for defeasibility of knowledge (through some notion of density) that gives us a reasonable logic and doesn't present this issues while being defined on a common space X .
- To solve this, we make explicit which is the subset of X which is compatible with each agent's information at a world.
- We make this through the use of **partitions** Π_1 and Π_2 .

A **topological partitional model** is a tuple

$$(X, \tau_1, \tau_2, \Pi_1, \Pi_2, V)$$

where X is a set, V is a valuation, each τ_i is a topology and each $\Pi_i \subseteq \tau_i$ is an open partition of X .

- We want to account for defeasibility of knowledge (through some notion of density) that gives us a reasonable logic and doesn't present this issues while being defined on a common space X .
- To solve this, we make explicit which is the subset of X which is compatible with each agent's information at a world.
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Our **density** condition is **not global** (relative to the whole space X) but local (relative to the cell of the partition):

For $U \subseteq X$ and $\pi \in \Pi_i$ we say that U is **π -locally dense** whenever $U \cap \pi$ is dense in the subspace topology

$$\tau_i|_{\pi} = \{V \cap \pi : V \in \tau_i\}.$$

Semantics for knowledge in topological-partitional models

For $i = 1, 2$ and $x \in X$, let $\pi \in \Pi_i$ be the unique cell with $x \in \pi$. We have:

$$x \in \llbracket K_i \phi \rrbracket \text{ iff } \exists U \in \tau_i, \pi\text{-locally dense such that } x \in U \subseteq \llbracket \phi \rrbracket.$$

The logic of knowledge in this setting is $S_{4.2K_1} + S_{4.2K_2}$.

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Semantics for knowledge in topological-partitional models

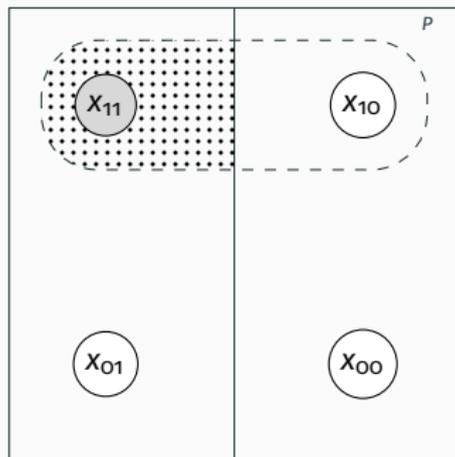
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EXAMPLE

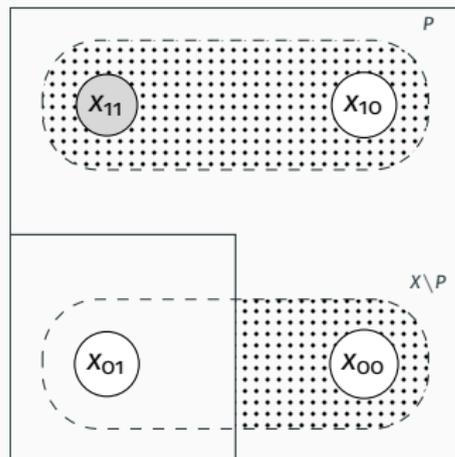
Agent 1



π_1

π_2

Agent 2



π_4

π_3

$$x_{11} \models K_1 p \wedge \neg K_2 p$$

Theorem

The logic of the knowledge-only fragment of topological parititonal models is the fusion logic $S4.2_{K_1} + S4.2_{K_1}$.

The infinite branching **quaternary tree** is an example of a generic model for this fragment.

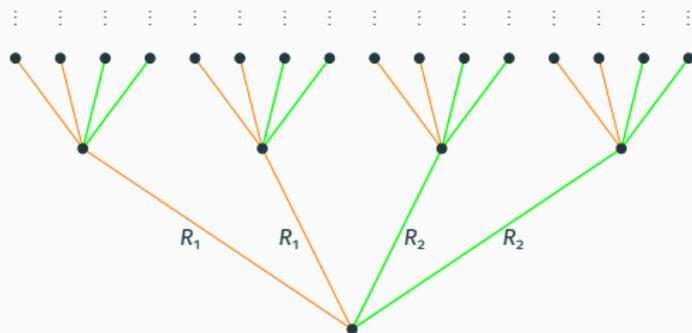


- Each topology τ_i is given by the set of R_i -upsets.
- The open partitions are given by the equivalence relation: $x \sim_i y$ iff there exists a z (zR_ix and zR_iy).

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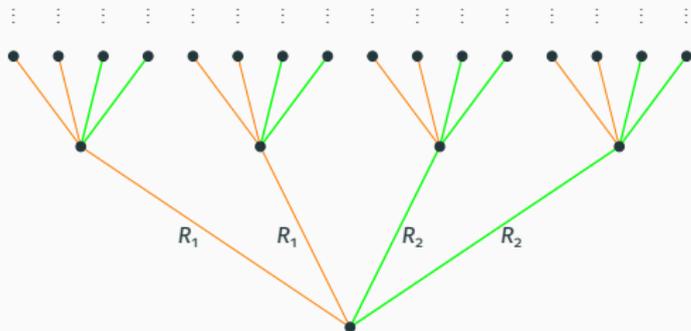


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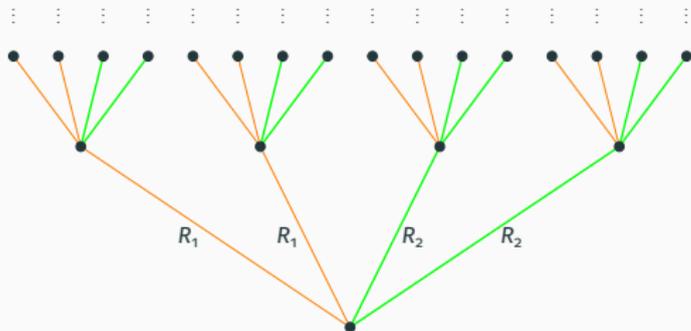


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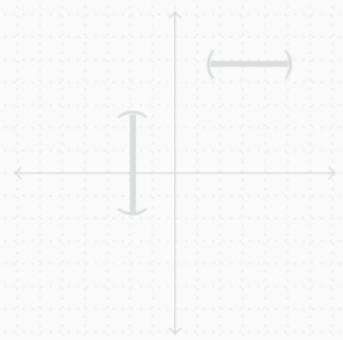


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- Another generic model is found on the **rational plane** $\mathbb{Q} \times \mathbb{Q}$.
- The **horizontal topology** τ_H is originated by the family of sets

$$\{U \times \{x\} : U \text{ open}, x \in \mathbb{Q}\}.$$

Similarly, the **vertical topology** τ_V is originated by the sets $\{x\} \times U$.

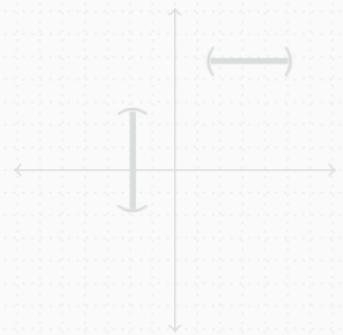


- We prove that there exists an open partition on $\mathbb{Q} \times \mathbb{Q}$ making it into a generic model for the knowledge fragment.

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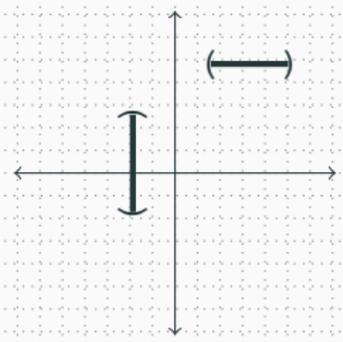


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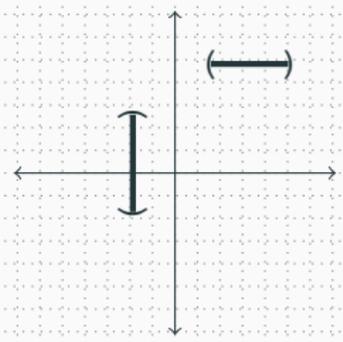


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- Certain topological spaces are generic enough to capture the logic of topo-e-models.
- A framework for multi-agent topological evidence logics that generalises the one agent case.

- Finding generic models with a designated subbasis.
- Strong completeness?
- Characterising a class of generic models for the two-agent logic.
- Complete logic of common knowledge for topological-partitional models.
- Dynamic two-agent topological-partitional models.

I never know how to end talks. Please clap now.

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