

# The Divergence Constraint in Magnetohydrodynamic Simulations

Jeaniffer Vides

PhD Supervisors: B. Nkonga, H. Guillard, E. Audit



January 30, 2013

# Outline

- 1 Introduction
- 2 Enforcing Divergence-Free Magnetic Field
  - Constrained Transport
  - Divergence Cleaning
- 3 Numerical Approximation and Results
  - Orszag-Tang
  - Kelvin-Helmholtz Instability
- 4 Conclusions

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# Magnetohydrodynamics (MHD) and Plasmas

- **Set of equations**

- Combination of Navier-Stokes equations and Maxwell's equations
- Derived by taking moments of the kinetic equation and some approximations
  - We do not ask what the plasma ions and electrons are doing separately
  - We describe the plasma as a single conducting fluid

- **Ideal MHD**

- Perfectly conducting fluid
  - Field line freezing
- Strongly collisional plasma
- Length and time scale restrictions

# Ideal MHD Equations

- Set of nonlinear hyperbolic equations:

$$\partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0 \quad (1)$$

$$\partial_t (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) + \nabla (p + \frac{1}{2} \mathbf{B} \cdot \mathbf{B}) - \nabla \cdot (\mathbf{B} \otimes \mathbf{B}) = 0 \quad (2)$$

$$\partial_t \varepsilon + \nabla \cdot [(\varepsilon + p + \frac{1}{2} \mathbf{B} \cdot \mathbf{B}) \mathbf{u} - (\mathbf{u} \cdot \mathbf{B}) \mathbf{B}] = 0 \quad (3)$$

$$\partial_t \mathbf{B} + \nabla \cdot (\mathbf{B} \otimes \mathbf{u} - \mathbf{u} \otimes \mathbf{B}) = 0 \quad (4)$$

The hydrodynamic pressure  $p$  is given by the equation of state

$$p = (\gamma - 1) \left( \varepsilon - \frac{\rho}{2} \mathbf{u} \cdot \mathbf{u} - \frac{1}{2} \mathbf{B} \cdot \mathbf{B} \right)$$

- Divergence constraint  $\nabla \cdot \mathbf{B} = 0$

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# Divergence Constraint

- Initial data satisfy  $\nabla \cdot \mathbf{B} = 0$   
 $\Rightarrow$  Exact solution will satisfy this constraint for all times

- Formulated in a strong sense

- $\partial_t \mathbf{B} + \nabla \cdot (\mathbf{B} \otimes \mathbf{u} - \mathbf{u} \otimes \mathbf{B}) = 0$  can be written as

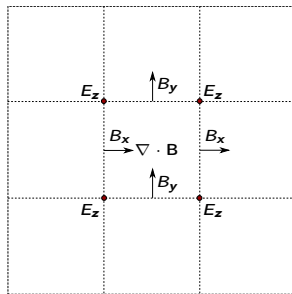
$$\partial_t \mathbf{B} + \nabla \times (\mathbf{B} \times \mathbf{u}) = 0 \quad (5)$$

- We have  $\nabla \cdot (\nabla \times \cdot) \equiv 0$

- Usually, discrete divergence of discrete curl is not exactly zero
  - $\nabla \cdot \mathbf{B}$  errors arise and may increase
  - Unphysical behavior
- Several methods aim to maintain this constraint numerically
  - Magnetic vector potential
  - Constrained transport**
  - Divergence cleaning**

# Constrained Transport <sup>1</sup>

- Staggered mesh formulation
  - Inherently divergence-free
  - Interpolation of  $\mathbf{B}$  to the control volume center needed in eq. (3) introduces an error in the conservation of the total energy



2D staggered grid

<sup>1</sup>S. Fromang, P. Hennebelle, and R. Teyssier. A high order Godunov scheme with constrained transport and adaptive mesh refinement for astrophysical MHD. *A&A*, 457:371-384, 2006.



## Divergence Cleaning<sup>2</sup>

- Cell-centered grid  $\Rightarrow$  divergence cleaning step
- Solve system (1)-(4), with equation (4) replaced by

$$\partial_t \mathbf{B} + \nabla \cdot (\mathbf{B} \otimes \mathbf{u} - \mathbf{u} \otimes \mathbf{B}) + \nabla \psi = 0 \quad (6)$$

$$\mathcal{D}(\psi) + \nabla \cdot \mathbf{B} = 0 \quad (7)$$

- GLM-MHD system consists of equations (1), (2), (6), (3), (7)

- **Hyperbolic correction**

$$\mathcal{D}(\psi) = \frac{1}{c_h^2} \partial_t \psi \quad \text{with } c_h \in (0, \infty)$$

- **Mixed correction**

$$\mathcal{D}(\psi) = \frac{1}{c_h^2} \partial_t \psi + \frac{1}{c_p^2} \psi \quad \text{with } c_h, c_p \in (0, \infty)$$

This choice offers both **propagation** and **dissipation** of divergence errors

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<sup>2</sup>A. Dedner, F. Kemm, D. Kröner, C.-D. Munz, T. Schnitzer, and M. Wesenberg. Hyperbolic divergence cleaning for the MHD equations. *J. Comput. Phys.*, 175(2):645-673, 2002.

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# Code

- HERACLES
  - Second-order finite volume method on structured grids
  - 3D parallel code used to simulate astrophysical flows
    - Hydrodynamics
    - MHD
    - Radiative transfer
    - Gravity
- Riemann problems for MHD
  - HLLC
  - **HLLD**
- Enforcing divergence-free magnetic field
  - Constrained transport
  - Divergence cleaning

# Orszag-Tang

**Constrained Transport**

**No Cleaning**

**Hyper GLM**

**Mixed GLM**

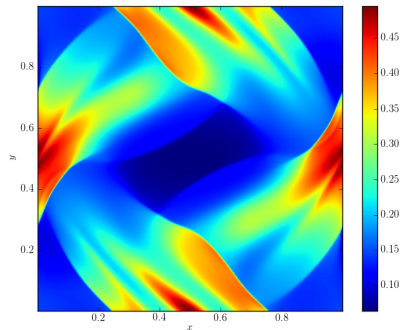
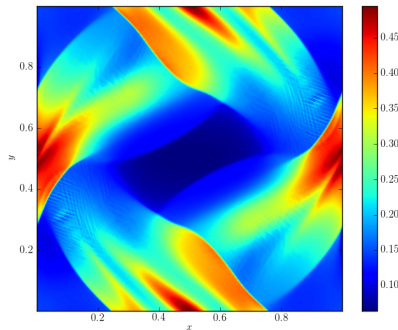
# Noise Comparison



## No Cleaning vs. Hyper GLM

Density [ $\rho$ ] at  $t = 0.25000s$

Density [ $\rho$ ] at  $t = 0.25000s$



# Kelvin-Helmholtz Instability

**Constrained Transport**  
Staggered Grid

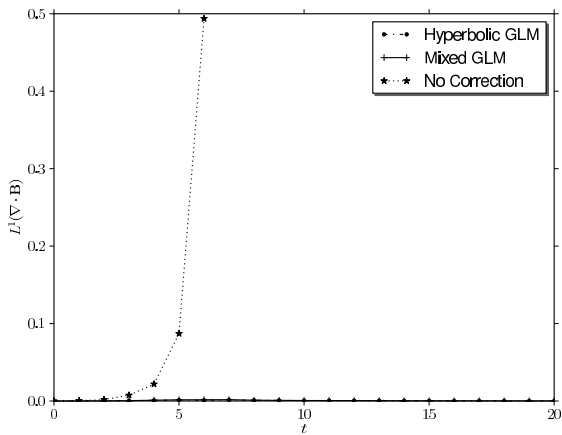
**No Cleaning**  
Centered Grid

# Kelvin-Helmholtz Instability

**Constrained Transport**

**Mixed GLM**

# Total Divergence





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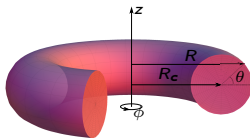
# Current<sup>3</sup> and Future Work

## Conclusions

- Showed the importance of maintaining  $\nabla \cdot \mathbf{B} = 0$  numerically
- New modules in HERACLES working as expected

## Future work

- Three-dimensional numerical scheme adapted to toroidal geometry
  - Curvilinear coordinates
  - Well-balanced
  - Large-scale parallel architectures
  - Cell-centered unstructured grid
    - ⇒ Less diffusive divergence cleaning method




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<sup>3</sup>J. Vides, B. Braconnier, E. Audit, C. Berthon, and B. Nkonga. A Godunov-type solver for the numerical approximation of gravitational flows, *submitted*

Thank you for your attention.

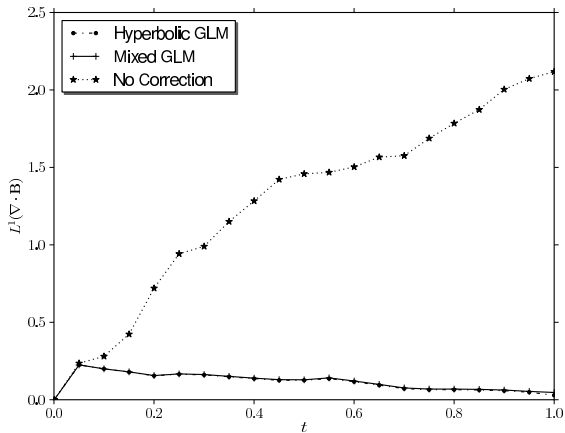
## The Divergence Constraint in MHD Simulations

Jeaniffer Vides

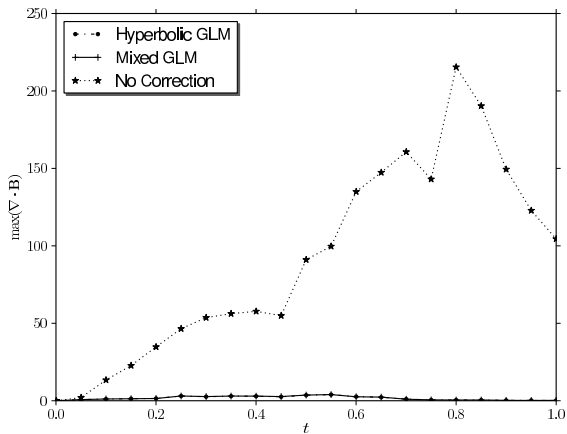
*INRIA, Maison de la Simulation, USR 3441, Gif-sur-Yvette, France*

*E-mail: [jeaniffer.vides@cea.fr](mailto:jeaniffer.vides@cea.fr)*

# Total Divergence

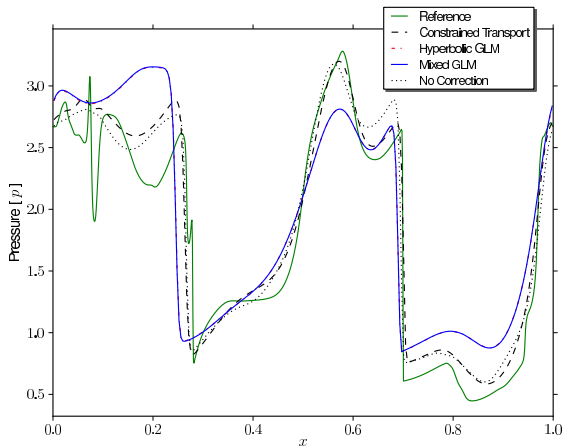
[Back](#)

# Maximum Divergence

[Back](#)

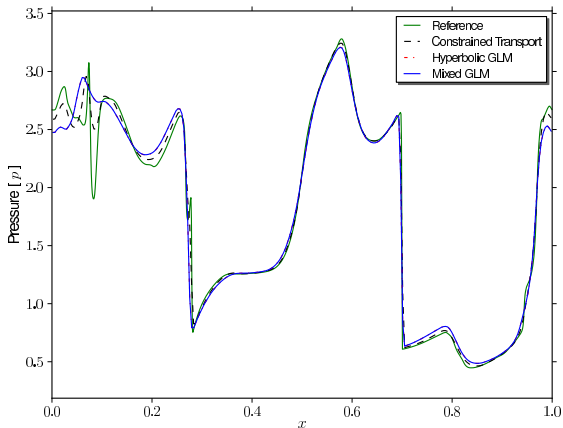
# Horizontal Cut (First Order)

- Horizontal cut at  $y = 0.3125$  at  $t = 0.5$  using the HLLD scheme

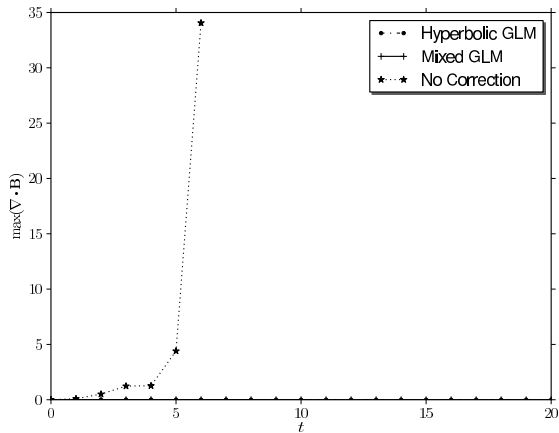


# Horizontal Cut (Second Order)

- Horizontal cut at  $y = 0.3125$  at  $t = 0.5$  using the HLLD scheme



# Maximum Divergence

[Back](#)



# Total Energy

