

Regularity of optimal transport maps on Riemannian manifolds

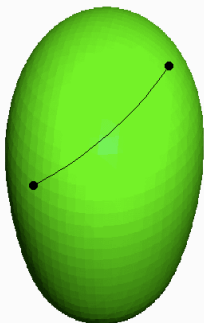
Ludovic Rifford

Université Nice - Sophia Antipolis
&
Institut Universitaire de France

Recent Development of nonlinear PDEs
(Canberra, November 2013)

The framework

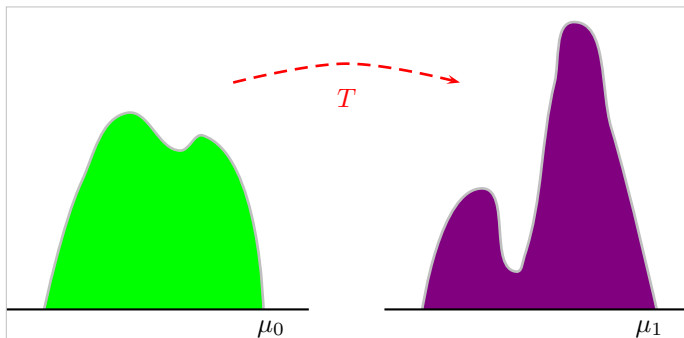
Let M be a **smooth connected (compact) manifold of dimension n** equipped with a **smooth Riemannian metric g** . For any $x, y \in M$, we define the **geodesic distance** between x and y , denoted by $d(x, y)$, as the minimum of the lengths of the curves joining x to y .



Transport maps

Let μ_0 and μ_1 be **probability measures** on M . We call **transport map** from μ_0 to μ_1 any measurable map $T : M \rightarrow M$ such that $T_{\#}\mu_0 = \mu_1$, that is

$$\mu_1(B) = \mu_0(T^{-1}(B)), \quad \forall B \text{ measurable } \subset M.$$



Quadratic Monge's Problem

Given two probability measures μ_0, μ_1 on M , find a transport map $T : M \rightarrow M$ from μ_0 to μ_1 which **minimizes** the quadratic cost ($c = d^2/2$)

$$\int_M c(x, T(x)) d\mu_0(x).$$

Quadratic Monge's Problem

Given two probabilities measures μ_0, μ_1 sur M , find a transport map $T : M \rightarrow M$ from μ_0 to μ_1 which **minimizes** the quadratic cost ($c = d^2/2$)

$$\int_M c(x, T(x)) d\mu_0(x).$$

Theorem (McCann '01)

*If μ_0 is absolutely continuous w.r.t. Lebesgue, then there exists a unique optimal transport map T from μ_0 to μ_1 . In fact, there is a **c-convex** function $\varphi : M \rightarrow \mathbb{R}$ satisfying*

$$T(x) = \exp_x(\nabla\varphi(x)) \quad \mu_0 \text{ a.e. } x \in M.$$

(Moreover, for a.e. $x \in M$, $\nabla\varphi(x)$ belongs to the injectivity domain at x .)

Purpose of the talk

- Regularity of optimal transport maps

Purpose of the talk

- Regularity of optimal transport maps
- Link with Monge-Ampère like equations

Purpose of the talk

- Regularity of optimal transport maps
- Link with Monge-Ampère like equations
- How the geometry enters the problem

Purpose of the talk

- Regularity of optimal transport maps
- Link with Monge-Ampère like equations
- How the geometry enters the problem
- State of the art

Purpose of the talk

- Regularity of optimal transport maps
- Link with Monge-Ampère like equations
- How the geometry enters the problem
- State of the art
- Open questions

Quadratic Monge's Problem in \mathbb{R}^n : Given two probability measures μ_0, μ_1 with compact supports in \mathbb{R}^n , we are concerned with transport maps $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ pushing forward μ_0 to μ_1 which **minimize** the transport cost

$$\int_{\mathbb{R}^n} |T(x) - x|^2 d\mu_0(x).$$

Quadratic Monge's Problem in \mathbb{R}^n : Given two probability measures μ_0, μ_1 with compact supports in \mathbb{R}^n , we are concerned with transport maps $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ pushing forward μ_0 to μ_1 which **minimize** the transport cost

$$\int_{\mathbb{R}^n} |T(x) - x|^2 d\mu_0(x).$$

Theorem (Brenier '91)

*If μ_0 is absolutely continuous with respect to the Lebesgue measure, there exists a unique optimal transport map with respect to the quadratic cost. In fact, there is a **convex** function $\psi : M \rightarrow \mathbb{R}$ such that*

$$T(x) = \nabla\psi(x) \quad \mu_0 \text{ a.e. } x \in \mathbb{R}^n.$$

Quadratic Monge's Problem in \mathbb{R}^n : Given two probability measures μ_0, μ_1 with compact supports in \mathbb{R}^n , we are concerned with transport maps $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ pushing forward μ_0 to μ_1 which **minimize** the transport cost

$$\int_{\mathbb{R}^n} |T(x) - x|^2 d\mu_0(x).$$

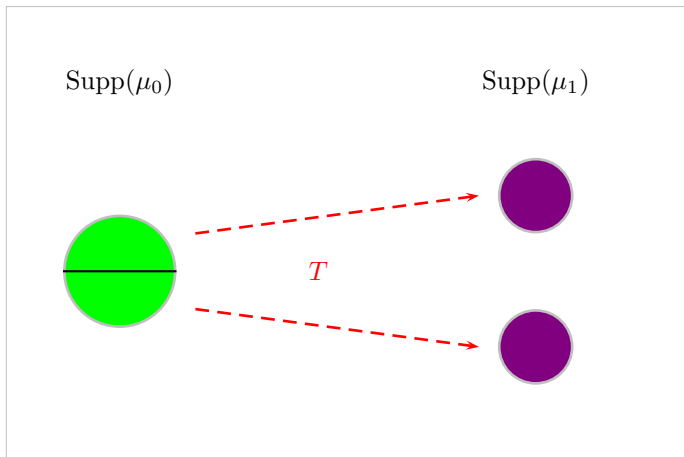
Theorem (Brenier '91)

*If μ_0 is absolutely continuous with respect to the Lebesgue measure, there exists a unique optimal transport map with respect to the quadratic cost. In fact, there is a **convex** function $\psi : M \rightarrow \mathbb{R}$ such that*

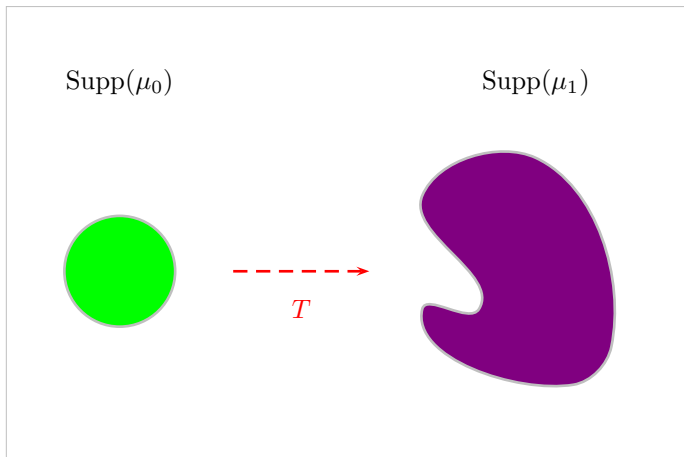
$$T(x) = \nabla\psi(x) \quad \mu_0 \text{ a.e. } x \in \mathbb{R}^n.$$

Necessary and sufficient conditions for regularity ?

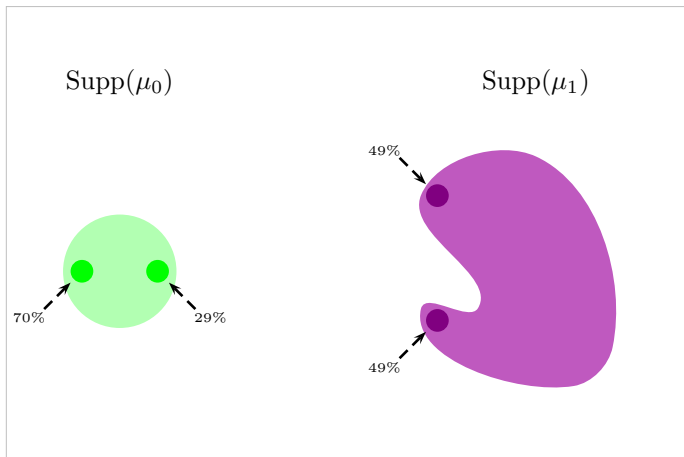
An obvious counterexample



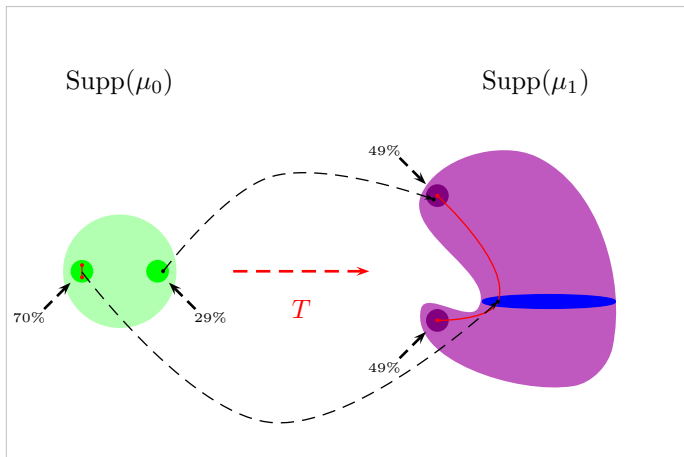
The convexity of the target is necessary



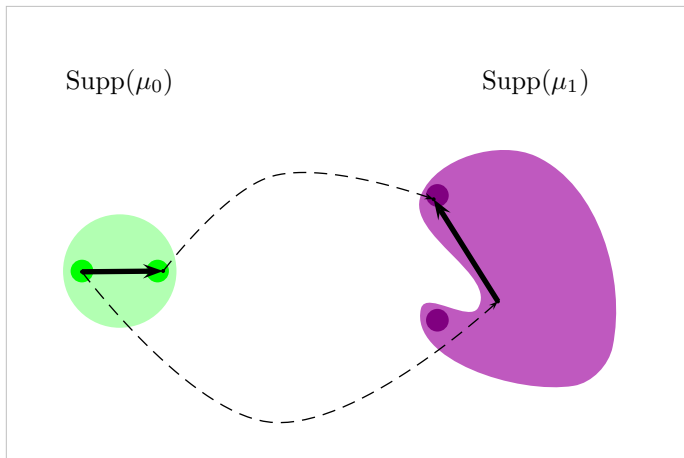
The convexity of the target is necessary



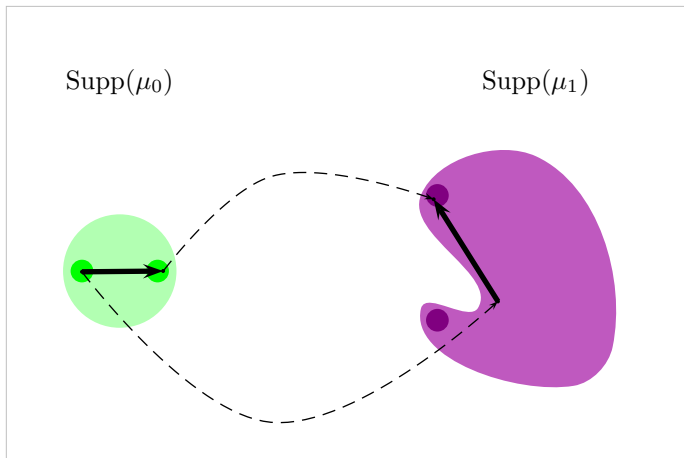
The convexity of the target is necessary



The convexity of the target is necessary

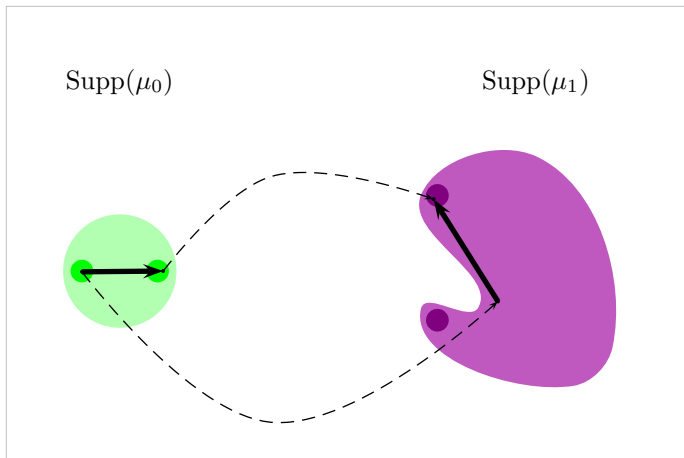


The convexity of the target is necessary



T gradient of a convex function

The convexity of the target is necessary



T gradient of a convex function $\implies \langle y-x, T(y)-T(x) \rangle \geq 0!!!$

Caffarelli's Regularity Theory

If μ_0 and μ_1 are associated with densities f_0, f_1 w.r.t. Lebesgue, then

$$T_{\#}\mu_0 = \mu_1 \iff \int_{\mathbb{R}^n} \zeta(T(x)) f_0(x) dx = \int_{\mathbb{R}^n} \zeta(y) f_1(y) dy \quad \forall \zeta.$$

$\rightsquigarrow \psi$ weak solution of the **Monge-Ampère equation** :

$$\det(\nabla^2 \psi(x)) = \frac{f_0(x)}{f_1(\nabla \psi(x))}.$$

Theorem (Caffarelli '90s)

Let Ω_0, Ω_1 be connected and bounded open sets in \mathbb{R}^n and f_0, f_1 be probability densities resp. on Ω_0 and Ω_1 such that $f_0, f_1, 1/f_0, 1/f_1$ are **essentially bounded**. Assume that μ_0 and μ_1 have respectively densities f_0 and f_1 w.r.t. Lebesgue and that Ω_1 is **convex**. Then the quadratic optimal transport map from μ_0 to μ_1 is continuous.

Back to Riemannian manifolds

Given two probability measures μ_0, μ_1 sur M , find a transport map $T : M \rightarrow M$ from μ_0 to μ_1 which minimizes the quadratic cost ($c = d^2/2$)

$$\int_M c(x, T(x)) d\mu_0(x).$$

Back to Riemannian manifolds

Given two probability measures μ_0, μ_1 sur M , find a transport map $T : M \rightarrow M$ from μ_0 to μ_1 which minimizes the quadratic cost ($c = d^2/2$)

$$\int_M c(x, T(x)) d\mu_0(x).$$

Definition

We say that the Riemannian manifold (M, g) satisfies the **Transport Continuity Property (TCP)** if for any pair of probability measures μ_0, μ_1 associated locally with **continuous positive densities** ρ_0, ρ_1 , that is

$$\mu_0 = \rho_0 \text{vol}_g, \quad \mu_1 = \rho_1 \text{vol}_g,$$

the optimal transport map from μ_0 to μ_1 is **continuous**.

Exponential mapping and injectivity domains

Let $x \in M$ be fixed.

- For every $v \in T_x M$, we define the **exponential** of v by

$$\exp_x(v) = \gamma_{x,v}(1),$$

where $\gamma_{x,v} : [0, 1] \rightarrow M$ is the unique geodesic starting at x with speed v .

Exponential mapping and injectivity domains

Let $x \in M$ be fixed.

- For every $v \in T_x M$, we define the **exponential** of v by

$$\exp_x(v) = \gamma_{x,v}(1),$$

where $\gamma_{x,v} : [0, 1] \rightarrow M$ is the unique geodesic starting at x with speed v .

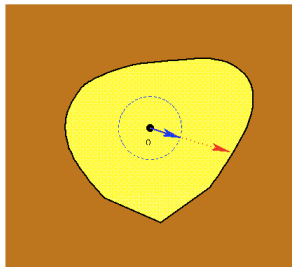
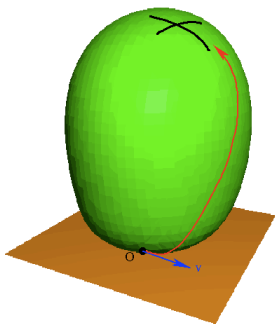
- We call **injectivity domain** at x , the subset of $T_x M$ defined by

$$\mathcal{I}(x) := \left\{ v \in T_x M \mid \exists t > 1 \text{ s.t. } \gamma_{tv} \text{ is the unique minim. geod. between } x \text{ and } \exp_x(tv) \right\}$$

It is a star-shaped (w.r.t. $0 \in T_x M$) bounded open set with Lipschitz boundary.

The distance to the cut locus

Using the exponential mapping, we can associate to each unit tangent vector its **distance to the cut locus**.



In that way, we define the so-called **injectivity domain** $\mathcal{I}(x)$ whose boundary is the **tangent cut locus** $\text{TCL}(x)$.

A necessary condition for **TCP**

Theorem (Figalli-R-Villani '10)

Let (M, g) be a smooth compact Riemannian manifold satisfying **TCP**. Then following properties hold:

- all the injectivity domains are convex,
- for any $x, x' \in M$, the function

$$F_{x,x'} : v \in \mathcal{I}(x) \longmapsto c(x, \exp_x(v)) - c(x', \exp_x(v))$$

is **quasiconvex** (its sublevel sets are always convex).

Almost characterization of quasiconvex functions

Lemma (Sufficient condition)

Let $U \subset \mathbb{R}^n$ be an open convex set and $F : U \rightarrow \mathbb{R}$ be a function of class C^2 . Assume that for every $v \in U$ and every $w \in \mathbb{R}^n \setminus \{0\}$ the following property holds :

$$\langle \nabla_v F, w \rangle = 0 \implies \langle \nabla_v^2 F w, w \rangle > 0.$$

Then F is quasiconvex.

Almost characterization of quasiconvex functions

Lemma (Sufficient condition)

Let $U \subset \mathbb{R}^n$ be an open convex set and $F : U \rightarrow \mathbb{R}$ be a function of class C^2 . Assume that for every $v \in U$ and every $w \in \mathbb{R}^n \setminus \{0\}$ the following property holds :

$$\langle \nabla_v F, w \rangle = 0 \implies \langle \nabla_v^2 F w, w \rangle > 0.$$

Then F is quasiconvex.

Lemma (Necessary condition)

Let $U \subset \mathbb{R}^n$ be an open convex set and $F : U \rightarrow \mathbb{R}$ be a function of class C^2 . Assume that F is quasiconvex. Then for every $v \in U$ and every $w \in \mathbb{R}^n \setminus \{0\}$ the following property holds :

$$\langle \nabla_v F, w \rangle = 0 \implies \langle \nabla_v^2 F w, w \rangle \geq 0.$$

Proof of the easy lemma

Proof.

Let $v_0, v_1 \in U$ be fixed. Set $v_t := (1 - t)v_0 + tv_1$, for every $t \in [0, 1]$. Define $h : [0, 1] \rightarrow \mathbb{R}$ by

$$h(t) := F(v_t) \quad \forall t \in [0, 1].$$

If $h \not\leq \max\{h(0), h(1)\}$, there is $\tau \in (0, 1)$ such that

$$h(\tau) = \max_{t \in [0, 1]} h(t) > \max\{h(0), h(1)\}.$$

Proof of the easy lemma

Proof.

Let $v_0, v_1 \in U$ be fixed. Set $v_t := (1 - t)v_0 + tv_1$, for every $t \in [0, 1]$. Define $h : [0, 1] \rightarrow \mathbb{R}$ by

$$h(t) := F(v_t) \quad \forall t \in [0, 1].$$

If $h \not\leq \max\{h(0), h(1)\}$, there is $\tau \in (0, 1)$ such that

$$h(\tau) = \max_{t \in [0, 1]} h(t) > \max\{h(0), h(1)\}.$$

There holds

$$\dot{h}(\tau) = \langle \nabla_{v_\tau} F, \dot{v}_\tau \rangle \quad \text{et} \quad \ddot{h}(\tau) = \langle \nabla_{v_\tau}^2 F \dot{v}_\tau, \dot{v}_\tau \rangle.$$

Since τ is a local maximum, one has $\dot{h}(\tau) = 0$.

Contradiction !!



The Ma-Trudinger-Wang tensor

The **MTW** tensor \mathfrak{G} is defined as

$$\mathfrak{G}_{(x,v)}(\xi, \eta) = -\frac{3}{2} \frac{d^2}{ds^2} \Big|_{s=0} \frac{d^2}{dt^2} \Big|_{t=0} c(\exp_x(t\xi), \exp_x(v + s\eta)),$$

for every $x \in M$, $v \in \mathcal{I}(x)$, and $\xi, \eta \in T_x M$.

The Ma-Trudinger-Wang tensor

The **MTW** tensor \mathfrak{G} is defined as

$$\mathfrak{G}_{(x,v)}(\xi, \eta) = -\frac{3}{2} \frac{d^2}{ds^2} \Big|_{s=0} \frac{d^2}{dt^2} \Big|_{t=0} c(\exp_x(t\xi), \exp_x(v + s\eta)),$$

for every $x \in M$, $v \in \mathcal{I}(x)$, and $\xi, \eta \in T_x M$.

Proposition (Villani '09, Figalli-R-Villani '10)

Let (M, g) be such that all injectivity domains are convex.

Then the following properties are equivalent:

- *All the functions $F_{x,x'}$ are quasiconvex.*
- *The **MTW** tensor \mathfrak{G} is $\succeq 0$, that is for any $x \in M$, $v \in \mathcal{I}(x)$, and $\xi, \eta \in T_x M$,*

$$\langle \xi, \eta \rangle_x = 0 \implies \mathfrak{G}_{(x,v)}(\xi, \eta) \geq 0.$$

When geometry enters the problem

Theorem (Loeper '06)

For every $x \in M$ and for any pair of unit orthogonal tangent vectors $\xi, \eta \in T_x M$, there holds

$$\mathfrak{G}_{(x,0)}(\xi, \eta) = \kappa_x(\xi, \eta),$$

where the latter denotes the **sectional curvature** of M at x along the plane spanned by $\{\xi, \eta\}$.

Corollary (Loeper '06)

$$\mathbf{TCP} \implies \mathfrak{G} \succeq 0 \implies \kappa \geq 0.$$

When geometry enters the problem

Theorem (Loeper '06)

For every $x \in M$ and for any pair of unit orthogonal tangent vectors $\xi, \eta \in T_x M$, there holds

$$\mathfrak{G}_{(x,0)}(\xi, \eta) = \kappa_x(\xi, \eta),$$

where the latter denotes the **sectional curvature** of M at x along the plane spanned by $\{\xi, \eta\}$.

Corollary (Loeper '06)

$$\mathbf{TCP} \implies \mathfrak{G} \succeq 0 \implies \kappa \geq 0.$$

Caution!!! $\kappa \geq 0 \not\Rightarrow \mathfrak{G} \succeq 0$.

Sufficient conditions for **TCP**

Theorem (Figalli-R-Villani '10)

Let (M, g) be a compact smooth Riemannian **surface**. It satisfies **TCP** if and only if the two following properties holds:

- all the injectivity domains are convex,
- $\mathcal{G} \succeq 0$.

Sufficient conditions for **TCP**

Theorem (Figalli-R-Villani '10)

Let (M, g) be a compact smooth Riemannian **surface**. It satisfies **TCP** if and only if the two following properties holds:

- all the injectivity domains are convex,
- $\mathfrak{S} \succeq 0$.

Theorem (Figalli-R-Villani '10)

Assume that (M, g) satisfies the two following properties:

- all its injectivity domains are **strictly convex**,
- the **MTW** tensor \mathfrak{S} is $\succ 0$, that is for any $x \in M, v \in \mathcal{I}(x)$, and $\xi, \eta \in T_x M$,

$$\langle \xi, \eta \rangle_x = 0 \implies \mathfrak{S}_{(x,v)}(\xi, \eta) > 0.$$

Then, it satisfies **TCP**.

Examples and counterexamples

Examples:

- Flat tori (Cordero-Erausquin '99)
- Round spheres (Loeper '06)
- Product of spheres (Figalli-Kim-McCann '13)
- Quotients of the above objects
- Perturbations of round spheres (Figalli-R-Villani '12)

Examples and counterexamples

Examples:

- Flat tori (Cordero-Erausquin '99)
- Round spheres (Loeper '06)
- Product of spheres (Figalli-Kim-McCann '13)
- Quotients of the above objects
- Perturbations of round spheres (Figalli-R-Villani '12)

Counterexamples:



Examples and counterexamples

Examples:

- Flat tori (Cordero-Erausquin '99)
- Round spheres (Loeper '06)
- Product of spheres (Figalli-Kim-McCann '13)
- Quotients of the above objects
- Perturbations of round spheres (Figalli-R-Villani '12)

Counterexamples:



Questions

- Does $\mathcal{G} \succeq 0 \implies \mathbf{TCP}$ in dimension ≥ 3 ?
- Smoother datas imply further regularity ?

Questions

- Does $\mathcal{G} \succeq 0 \implies \mathbf{TCP}$ in dimension ≥ 3 ?
- Smoother datas imply further regularity ?
- How is the set of metrics satisfying $\mathcal{G} \succ 0$?
- Does $\mathcal{G} \succeq 0$ imply convexity of injectivity domains ?
- Does $\mathcal{G} \succeq 0$ imply more topological obstructions than $\kappa \geq 0$?

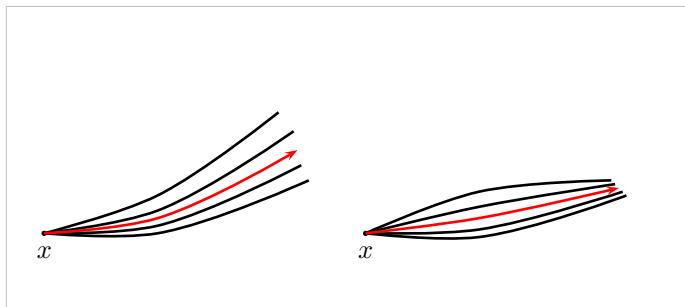
- Does $\mathfrak{G} \succeq 0 \implies \mathbf{TCP}$ in dimension ≥ 3 ?
- Smoother datas imply further regularity ?
- How is the set of metrics satisfying $\mathfrak{G} \succ 0$?
- Does $\mathfrak{G} \succeq 0$ imply convexity of injectivity domains ?
- Does $\mathfrak{G} \succeq 0$ imply more topological obstructions than $\kappa \geq 0$?

Focalization is the major obstacle

Focalization

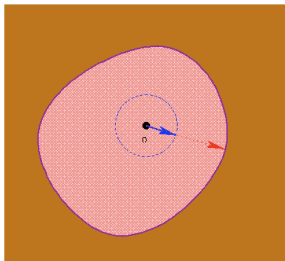
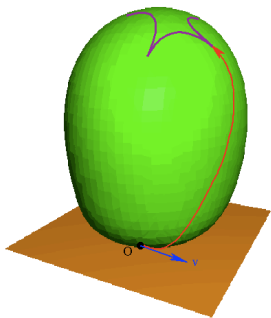
Definition

Let $x \in M$ and v be a unit tangent vector in $T_x M$. The vector v is **not conjugate** at time $t \geq 0$ if for any $t' \in [0, t + \delta]$ ($\delta > 0$ small) the geodesic from x to $\gamma(t')$ is locally minimizing.



The distance to the conjugate locus

Again, using the exponential mapping, we can associate to each unit tangent vector its **distance to the conjugate locus**.

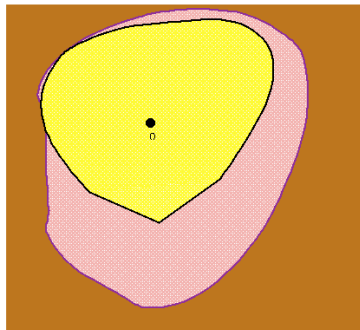


In that way, we define the so-called **nonfocal domain** $\mathcal{NF}(x)$ whose boundary is the **tangent conjugate locus** $\text{TFL}(x)$.

Fundamental inclusion

The following inclusion holds

injectivity domain \subset nonfocal domain.



Stay away property

Theorem

Let (M, g) be a compact Riemannian manifold satisfying **TCP** and μ_0, μ_1 two probability measures associated with **smooth positive densities**. Assume that the continuous transport map $T : M \rightarrow M$ satisfies

$$T(x) \notin TFL(x) \quad \forall x \in M.$$

Then T is smooth.

Stay away property

Theorem

Let (M, g) be a compact Riemannian manifold satisfying **TCP** and μ_0, μ_1 two probability measures associated with **smooth positive densities**. Assume that the continuous transport map $T : M \rightarrow M$ satisfies

$$T(x) \notin TFL(x) \quad \forall x \in M.$$

Then T is smooth.

The potential $\psi : M \rightarrow \mathbb{R}$ satisfying $T(x) = \exp_x(\nabla\psi(x))$ is the solution of the Monge-Ampère like equation ($c = d^2$)

$$\begin{aligned} \det(\nabla^2\psi(x) + \nabla_{xx}c(x, T(x))) \\ = |\det(\nabla_{xy}c(x, T(x)))| \frac{f_0(x)}{f_1(T(x))}. \end{aligned}$$

Thank you for your attention !!